

Universität Regensburg Mathematik



Causal variational principles on measure spaces

Felix Finster

Preprint Nr. 34/2008

CAUSAL VARIATIONAL PRINCIPLES ON MEASURE SPACES

FELIX FINSTER

NOVEMBER 2008

ABSTRACT. We introduce a class of variational principles on measure spaces which are causal in the sense that they generate a relation on pairs of points, giving rise to a distinction between spacelike and timelike separation. General existence results are proved. It is shown in examples that minimizers need not be unique. Counter examples to compactness are discussed. The existence results are applied to variational principles formulated in indefinite inner product spaces.

CONTENTS

1. The Causal Variational Principle with Two Prescribed Eigenvalues	2
1.1. Introduction and Basic Definitions	2
1.2. Existence of Minimizers	3
1.3. Non-Uniqueness in the Discrete Setting	7
1.4. The Continuum Variational Principle and its Hilbert Space Formulation	8
1.5. Non-Uniqueness and Non-Triviality of Minimizers	9
2. A General Class of Causal Variational Principles	17
2.1. Definitions and Statement of Results	17
2.2. Counter Examples to Compactness	20
2.3. The Moment Measures and the Possibility of Bubbling	23
2.4. Existence Proofs	30
2.5. Remarks and Open Problems	31
3. Variational Principles in Indefinite Inner Product Spaces	32
3.1. Definitions and Statement of Results	33
3.2. Reformulation in Terms of Local Correlation Matrices	35
3.3. Reconstruction of the Fermion System	38
4. A Variational Principle in Infinite Space-Time Volume	38
References	46

Causal variational principles on measure spaces arise in the context of relativistic quantum theory. But they are also interesting from a purely mathematical perspective as a class of nonlinear variational principles whose minimizers have a surprisingly rich and so far largely unexplored structure. The goal of the present article is to give a mathematical introduction to these variational principles and to develop the existence theory (Chapters 1 and 2). The physical applications will be obtained by reformulating the variational principles in indefinite inner product spaces (Chapters 3 and 4). Our

Supported in part by the Deutsche Forschungsgemeinschaft.

results will be illustrated by a number of examples and counter examples, which also show that the minimizers are in general non-trivial and not unique.

1. THE CAUSAL VARIATIONAL PRINCIPLE WITH TWO PRESCRIBED EIGENVALUES

1.1. Introduction and Basic Definitions. In order to give an easily accessible introduction to the basic ideas and methods, we begin with the simplest interesting example, the so-called causal variational principle with two prescribed eigenvalues (the general systems will be introduced in Chapter 2). Let (M, μ) be a measure space of total volume $\mu(M) = 1$. For a given parameter $\beta \in [0, 1)$ and an integer $f \geq 2$, we let $\mathcal{F} \subset \text{Mat}(\mathbb{C}^f)$ be the set of all Hermitian $f \times f$ -matrices of rank at most two, whose non-trivial eigenvalues are equal to 1 and $-\beta$. Consider the set of matrix-valued functions

$$\mathbb{M} = \{F : M \rightarrow \mathcal{F} \text{ measurable}\}.$$

For any $F \in \mathbb{M}$ and $x, y \in M$, the matrix product

$$A_{xy} = F(x) \cdot F(y) \tag{1.1}$$

is of rank at most two. Thus counting with algebraic multiplicities, its eigenvalues are

$$\lambda_+^{xy}, \lambda_-^{xy}, \underbrace{0, \dots, 0}_{f-2 \text{ times}} \quad \text{with} \quad \lambda_{\pm}^{xy} \in \mathbb{C}$$

(note that the matrix A_{xy} is Hermitian only in the special case that $F(x)$ and $F(y)$ commute, and thus the λ_{\pm}^{xy} will in general be complex). Clearly, the functions λ_{\pm}^{xy} are measurable in x and y . Thus introducing

the Lagrangian	$\mathcal{L}[A_{xy}] = \frac{1}{2} (\lambda_+^{xy} - \lambda_-^{xy})^2$	(1.2)
the action	$\mathcal{S}[F] = \iint_{M \times M} \mathcal{L}[A_{xy}] d\mu(x) d\mu(y),$	

we obtain a non-negative functional \mathcal{S} on \mathbb{M} . Our variational principle is to

minimize \mathcal{S} on \mathbb{M} .

We are interested in the following questions:

- What is the infimum of the action? Is the infimum attained?
- Provided a minimizer exists, what is its regularity? Is the minimizer unique? What is the structure of the minimizers?

Before addressing these questions, we explain the form of the Lagrangian and discuss a few properties of our variational principle. We first point out that, since we prescribed its eigenvalues, every matrix in \mathcal{F} has sup-norm one, and thus

$$|\lambda_{\pm}^{xy}| \leq \|F(x)F(y)\| \leq \|F(x)\| \|F(y)\| = 1.$$

Hence the Lagrangian is bounded, $\mathcal{L} \in L^\infty(M \times M, \mathbb{R})$, and the action is finite. Next, the transformations

$$\lambda_+^{xy} + \lambda_-^{xy} = \text{Tr}(F(x)F(y)) = \overline{\text{Tr}(F(y)F(x))} = \overline{\text{Tr}(F(x)F(y))} = \overline{\lambda_+^{xy}} + \overline{\lambda_-^{xy}}$$

show that the λ_+^{xy} and λ_-^{xy} are either both real, or else they form a complex conjugate pair. This distinction gives rise to a notion of causality.

Definition 1.1. *Two points $x, y \in M$ are called **timelike** and **spacelike** separated if the roots λ_{\pm}^{xy} of the characteristic polynomial of A_{xy} are real or non-real, respectively.*

Let us verify that this notion is symmetric in x and y . The first method is to note that the λ_{\pm}^{xy} are uniquely determined as the solutions of the two equations

$$\lambda_{+}^{xy} + \lambda_{-}^{xy} = \text{Tr}(A_{xy}) \quad \text{and} \quad (\lambda_{+}^{xy})^2 + (\lambda_{-}^{xy})^2 = \text{Tr}(A_{xy}^2).$$

Substituting (1.1) and cyclically commuting the arguments of the traces, one sees that the traces are invariant under exchanging x and y . In other words, the matrices A_{xy} and A_{yx} have the same spectrum, showing that our notion of causality is indeed symmetric in x and y . Alternatively, this can be seen from the matrix identity $\det(BC - \lambda \mathbf{1}) = \det(CB - \lambda \mathbf{1})$ (see for example [6, Section 3]).

If x and y are spacelike separated, we just saw that the λ_{\pm}^{xy} form a complex conjugate pair. Hence the absolute values of λ_{+}^{xy} and λ_{-}^{xy} coincide, and thus the Lagrangian \mathcal{L} in (1.2) vanishes. In other words, pairs (x, y) with spacelike separation drop out of the Lagrangian and thus do not enter the action. We refer to this fact that our variational principle is *causal*. This causality can be seen in analogy to relativity, where space-time points with spacelike separation cannot influence each other via the physical equations. This analogy will become clearer in Chapter 3, when variational principles in indefinite inner product spaces are considered. Until then, we shall focus on the mathematical properties of our variational principle.

Qualitatively, since the Lagrangian vanishes for spacelike separation, our variational principle tries to achieve that as many pairs of points as possible have spacelike separation. On the other hand, in the special case $F(x) = F(y)$, the matrix A_{xy} has the non-zero eigenvalues 1 and β^2 , showing that x and y will have timelike separation if $F(x)$ and $F(y)$ are sufficiently close to each other. Thus there are competing mechanisms, and this will lead to mathematically interesting effects.

Another point of mathematical interest is that our variational principle generates mathematical structures on M . Note that (M, μ) is merely a measure space, but we do not assume a topology. But a given minimizer F induces a topology on M (namely $F^{-1}(\mathcal{O})$, where \mathcal{O} denotes the set of all open subsets of \mathcal{F}), and furthermore F induces the causal structure of Definition 1.1. Thus a minimizer *generates on M a topological and causal structure*. In order to better understand this structure formation, one needs to clarify the freedom in choosing the minimizers of the variational principle. In particular, if our variational principle allowed to distinguish a specific minimizer F (determined modulo isomorphisms of the measure space (M, μ)), this would give rise to a canonical topology and a canonical causal structure on M .

1.2. Existence of Minimizers. This section is devoted to the proof of the following general existence theorem.

Theorem 1.2. *There is a function $F \in \mathbb{M}$ such that*

$$\mathcal{S}[F] = \inf_{\mathbb{M}} \mathcal{S}.$$

The most obvious idea for the proof is to try the direct method of the calculus of variations. Thus let $F_k \in \mathbb{M}$ be a minimizing sequence, i.e.

$$\lim_{k \rightarrow \infty} \mathcal{S}[F_k] = \inf_{\mathbb{M}} \mathcal{S}.$$

The proof would be completed if we found a convergent subsequence F_{n_k} and could prove that \mathcal{S} was lower semi-continuous. The following consideration explains why this method does not seem to work. If our subsequence converged in the weak sense, $F_{n_k} \rightharpoonup F$, the spectral properties of the matrices $F_{n_k}(x)$ could not be controlled in

the limit. Thus the matrix $F(x)$ would in general no longer have the eigenvalues 1 and $-\beta$, and thus F would not be the desired minimizer. This explains why for a useful notion of convergence in \mathcal{F} it seems necessary to consider the topology induced by the sup-distance function

$$d(F, G) = \sup_{x \in M} \|F(x) - G(x)\|, \quad (1.3)$$

where $\|\cdot\|$ is a matrix norm on \mathcal{F} . Now suppose that ϕ is an isomorphism of the measure space (M, μ) (i.e. a measure preserving bijection of M). Then for any given $F_0 \in \mathbb{M}$, the function $F_0 \circ \phi$ is again in \mathbb{M} , and both functions have the same action. More generally, \mathcal{S} is constant on the orbit \mathbb{U} of F_0 under the action of such isomorphisms,

$$\mathbb{U} := \{F_0 \circ \phi \mid \phi \text{ isomorphism of } (M, \mu)\} \subset \mathbb{M}. \quad (1.4)$$

The problem is that the orbits (1.4) are in general not compact in the topology (1.3). To see this in a simple example, we take $M = [0, 1)$ with the Lebesgue measure and choose $F_0 \in \mathbb{M}$ as a function which takes two different values $p, q \in \mathcal{F}$, being constant on the intervals $[0, \frac{1}{2})$ and $[\frac{1}{2}, 1)$. We consider the one-parameter family of isomorphisms $\phi_\lambda(x) = (x + \lambda) \bmod 1$ with $\lambda \in [0, 1)$. Then the functions $F_\lambda(x) := F_0 \circ \phi_\lambda$ are all in \mathbb{U} , but for any $\lambda \neq \mu$ their distance is a non-zero constant, $d(F_\lambda, F_\mu) = d(p, q) > 0$. Hence there is even an uncountable family of functions in \mathbb{U} which has no convergent subsequence.

Our method to avoid the above problem is to translate the functions F_k into measures ρ_k on \mathcal{F} , as we now explain. We first note that in the case $0 < \beta < 1$, every point $p \in \mathcal{F}$ is a $f \times f$ -matrix, which is characterized by the two orthogonal eigenspaces corresponding to the eigenvalues 1 and $-\beta$. Characterizing p equivalently by the first eigenspace and the linear span of both eigenspaces, we can identify p with a point of the *flag manifold* $\mathcal{F}^{1,2}(\mathbb{C}^f)$ (for the detailed definition we refer to [11, Chapter I, §3.1]). Likewise, in the case $\beta = 0$, every point $p \in \mathcal{F}$ is characterized by the eigenspace corresponding to the eigenvalue one, and thus \mathcal{F} can be identified with the Grassmannian $\mathcal{F}^1(\mathbb{C}^f)$. In each case, this identification is useful because it makes \mathcal{F} into a smooth compact manifold. Moreover, \mathcal{F} is a homogeneous space, meaning that the mapping

$$p \rightarrow UpU^{-1} \quad \text{with} \quad U \in U(f) \quad (1.5)$$

defines a transitive action of the group $U(f)$ on \mathcal{F} . We introduce on \mathcal{F} a Riemannian metric g which is invariant under this group action and denote the corresponding invariant measure by $\mu_{\mathcal{F}}$. For simplicity, we normalize g such that $\mu_{\mathcal{F}}(\mathcal{F}) = 1$. Taking the infimum of the lengths of curves gives on \mathcal{F} a distance function

$$d : \mathcal{F} \times \mathcal{F} \rightarrow \mathbb{R}_0^+.$$

The topology of \mathcal{F} is generated by the open balls $B_\varepsilon(y)$ of distance radius ε centered at $y \in \mathcal{F}$.

Next to any $F \in \mathbb{M}$ we introduce a measure ρ on \mathcal{F} by defining that $\Omega \subset \mathcal{F}$ is measurable if and only if $F^{-1}(\Omega) \subset M$ is measurable and by setting

$$\rho(\Omega) = \mu(F^{-1}(\Omega)). \quad (1.6)$$

Clearly, $\rho(\mathcal{F}) = \mu(M) = 1$. The advantage of working with ρ is that it does not depend on isomorphisms of (M, μ) , as the simple calculation

$$\mu((F \circ \phi)^{-1}(\Omega)) = \mu(\phi^{-1}(F^{-1}(\Omega))) = \mu(F^{-1}(\Omega))$$

shows. Furthermore, our action can be expressed in terms of the measure ρ by

$$\mathcal{S}(\rho) = \iint_{\mathcal{F} \times \mathcal{F}} \mathcal{L}[p \cdot q] d\rho(p) d\rho(q), \quad (1.7)$$

where $p \cdot q$ is the matrix multiplication of elements of \mathcal{F} . Our strategy is to first construct a minimizer of (1.7) and then to construct the corresponding minimizer F of the original variational problem.

Let $C^0(\mathcal{F})$ be the Banach space of continuous functions on \mathcal{F} , equipped with the sup-norm. We consider every measure ρ_k according to $\rho_k(f) = \int_{\mathcal{F}} f d\rho_k$ (with $f \in C^0(\mathcal{F})$) as a linear functional on $C^0(\mathcal{F})$. The relations

$$|\rho_k(f)| \leq \|f\| \rho_k(\mathcal{F}) = \|f\|, \quad \rho_k(1_{\mathcal{F}}) = \rho_k(\mathcal{F}) = 1 \quad (1.8)$$

(where $1_{\mathcal{F}} : \mathcal{F} \rightarrow \mathbb{R}$ is the constant function one) yield that the ρ_k are continuous functionals and $\|\rho_k\|_{C^0(\mathcal{F})^*} = 1$. The positivity of the measures ρ_k is expressed by

$$\rho_k(f) \geq 0 \quad \text{for all } f \in C^0(\mathcal{F}) \text{ with } f \geq 0. \quad (1.9)$$

The Banach-Alaoglu theorem [14] yields a subsequence, for simplicity again denoted by ρ_k , which converges in the weak-* topology; that is, for every $f \in C^0(\mathcal{F})$ the series $\rho_k(f)$ converges. Thus by $\rho(f) = \lim_k \rho_k(f)$ we can define a functional on $C^0(\mathcal{F})$. By the Riesz representation theorem [15], there is a regular Borel measure ρ on \mathcal{F} such that

$$\rho(f) = \int_{\mathcal{F}} f d\rho \quad \text{for all } f \in C^0(\mathcal{F}).$$

From (1.8) one sees that ρ is normalized to $\rho(\mathcal{F}) = 1$. Furthermore, taking the limit $n \rightarrow \infty$ in (1.9) one sees that ρ is a positive measure. We conclude that there is a subsequence ρ_k and a positive normalized regular Borel measure such that

$$\int_{\mathcal{F}} f d\rho_k \rightarrow \int_{\mathcal{F}} f d\rho \quad \text{for all } f \in C^0(\mathcal{F}).$$

Since the function $\mathcal{L}[p \cdot q]$ with \mathcal{L} according to (1.2) is continuous in both arguments $p, q \in \mathcal{F}$, we conclude that $\mathcal{S}(\rho_k) \rightarrow \mathcal{S}(\rho)$. We have thus proved the following result.

Lemma 1.3. *There is a positive normalized regular Borel measure ρ on \mathcal{F} such that*

$$\iint_{\mathcal{F} \times \mathcal{F}} \mathcal{L}[p \cdot q] d\rho(p) d\rho(q) = \inf_{\mathcal{F}} S[F].$$

The remaining step is to “realize” the measure ρ by a function $F \in \mathbb{M}$ as follows.

Lemma 1.4. *There is a measurable function $F \in \mathbb{M}$ such that the measure ρ of Lemma 1.3 has the representation*

$$\rho(\Omega) = \mu(F^{-1}(\Omega)) \quad \text{for every Borel set } \Omega \subset \mathcal{F}.$$

Proof. We recall that a measurable set $\Omega \subset \mathbb{M}$ is called an *atom* if $\mu(\Omega) > 0$ and if every subset $K \subset \Omega$ with $\mu(K) < \mu(\Omega)$ has measure zero (cf. [10, Section 40]). A measure is said to be *atomic* if every set of non-zero measure contains an atom. Conversely, a measure is *non-atomic* if it contains no atoms. The measure μ can be decomposed into the sum of an atomic measure (μ^d, M^d) and a non-atomic measure (μ^c, M^c) in the sense that

$$M = M^d \dot{\cup} M^c \quad \text{and} \quad \mu = \mu^d + \mu^c \quad (1.10)$$

(see [12] for a proof in general measure spaces). Furthermore, an exhaustion argument (see [10, Section 42 (2)]) shows that

$$\text{For all } \alpha \in [0, \mu^c(M^c)] \text{ there is a measurable set } \Omega \subset M^c \text{ with } \mu^c(\Omega) = \alpha. \quad (1.11)$$

In order to treat the atomic part, we denote the atoms of the measure (μ^d, M^d) by \mathfrak{A} . Since every element $A \in \mathfrak{A}$ has measure $\mu^d(A) > 0$ and

$$\sum_{A \in \mathfrak{A}} \mu^d(A) = \mu(M^d) \leq 1,$$

the set \mathfrak{A} is at most countable. Furthermore, by modifying the functions F_k on sets of measure zero we can arrange that for every $A \in \mathfrak{A}$, the set $F_k(A)$ consist of just one point, for simplicity again denoted by $F_k(A)$. For any $A \in \mathfrak{A}$ we consider the series $F_k(A) \in \mathcal{F}$. Since \mathcal{F} is compact, this series has an accumulation point. Using that \mathfrak{A} is at most countable, a diagonal series argument yields that, possibly after choosing again a subsequence of $(F_k)_{n \in \mathbb{N}}$, for every $A \in \mathfrak{A}$ the series $F_k(A)$ converges in \mathcal{F} as $k \rightarrow \infty$. Setting $f(A) = \lim_{k \rightarrow \infty} F_k(A)$, it follows that for every $\varepsilon > 0$ and $y \in \mathcal{F}$,

$$\rho(B_\varepsilon(y)) = \lim_{k \rightarrow \infty} \rho_k(B_\varepsilon(y)) \geq \sum_{A \in \mathfrak{A} \text{ with } f(A)=y} \mu^d(A).$$

Since ρ is a regular Borel measure, we can let $\varepsilon \rightarrow 0$ to obtain the same bound for $\rho(\{y\})$. Hence subtracting a sum of Dirac measures,

$$\rho^c = \rho - \sum_{A \in \mathfrak{A}} \mu^d(A) \delta_{f(A)}, \quad (1.12)$$

the resulting measure ρ^c on \mathcal{F} is again positive. Defining the function F on M^d by

$$F|_{M^d} : M^d \rightarrow \mathcal{F} : A \mapsto f(A),$$

it remains to construct a function $g := F|_{M^c} : M^c \rightarrow \mathcal{F}$ such that

$$\rho^c(\Omega) = \mu^c(g^{-1}(\Omega)) \quad \text{for every Borel set } \Omega \subset \mathcal{F}. \quad (1.13)$$

To handle the non-atomic measure μ^c , we proceed by induction in k . In the first step $k = 1$, we decompose \mathcal{F} into a disjoint finite union of non-empty Borel sets of bounded distance diameter,

$$\mathcal{F} = \mathcal{F}_1^1 \dot{\cup} \dots \dot{\cup} \mathcal{F}_{l_{\max}(1)}^1 \quad \text{with} \quad \text{diam}(\mathcal{F}_l^1) < 1.$$

Since μ^c is non-atomic and

$$\mu^c(M^c) = 1 - \sum_{A \in \mathfrak{A}} \mu^d(A) \stackrel{(1.12)}{=} \rho^c(\mathcal{F}),$$

we can apply (1.11) iteratively to decompose M^c into a disjoint union of measurable sets $M_1^1, \dots, M_{l_{\max}(1)}^1$ with $\mu^c(M_l^1) = \rho^c(\mathcal{F}_l^1)$. Of every set \mathcal{F}_l^1 we choose a point y_l^1 and define a step function $g_1 : M^c \rightarrow \mathcal{F}$ by $g_1|_{M_l^1} \equiv y_l^1$, $l = 1, \dots, l_{\max}(1)$.

For the iteration step $(k-1) \rightarrow k$ we decompose each of the sets $\mathcal{F}_1^{k-1}, \dots, \mathcal{F}_{l_{\max}(k-1)}^{k-1}$ into sets of smaller diameter to obtain a decomposition of \mathcal{F} of the form

$$\mathcal{F} = \mathcal{F}_1^k \dot{\cup} \dots \dot{\cup} \mathcal{F}_{l_{\max}(k)}^k \quad \text{with} \quad \text{diam}(\mathcal{F}_l^k) < \frac{1}{k}.$$

Again using (1.11), we subdivide the sets M_l^{k-1} into smaller sets $M_1^k, \dots, M_{l_{\max}(k)}^k$ with the property $\mu^c(M_l^k) = \rho^c(\mathcal{F}_l^k)$. Of every set \mathcal{F}_l^k we again choose a point y_l^k and define a step function $g_k : M^d \rightarrow \mathcal{F}$ by $g_k|_{M_l^k} \equiv y_l^k$, $l = 1, \dots, l_{\max}(k)$.

This inductive procedure gives a series of step functions $(g_k)_{k \in \mathbb{N}}$. By construction, this series converges uniformly to a measurable function $g : M^d \rightarrow \mathcal{F}$. Furthermore, for any Borel set $\Omega \subset \mathcal{F}$,

$$\mu^c(g^{-1}(\Omega)) \xleftarrow{k \rightarrow \infty} \sum_{y_l^k \in \Omega} \mu^c(M_l^k) = \sum_{y_l^k \in \Omega} \rho^c(\mathcal{F}_l^k) \xrightarrow{k \rightarrow \infty} \rho^c(\Omega).$$

Thus g satisfies (1.13), completing the proof. \square

This completes the proof of Theorem 1.2.

1.3. Non-Uniqueness in the Discrete Setting. We now discuss the uniqueness problem in the case when the measure μ is discrete. We begin with the simple example where $M = \{1\}$ consists of only one point. In this case, every function $F \in \mathbb{M}$ can be identified with a point $F(1) \in \mathcal{F}$. All these functions give the same value $\mathcal{S} = \frac{1}{2}(1 - \beta^2)^2$ of the action, and thus the minimizer is clearly not unique. However, since according to (1.5) the $U(f)$ -symmetry group acts transitively on \mathcal{F} , all the minimizers can be obtained from each other by a suitable $U(f)$ -transformation. Thus the minimizer is unique up to $U(f)$ -transformations on \mathcal{F} .

The next example gives a connection to a problem already studied in the literature and gives a good intuition for the mechanisms in our variational principle.

Example 1.5. (*Maximizing distances of points on S^2*) We choose $f = 2$, $\beta = 0$ and let $M = \{1, \dots, m\}$ be a finite set with the normalized counting measure $\mu(\{1\}) = \dots = \mu(\{m\}) = \frac{1}{m}$. Then every $F(x)$ is a Hermitian 2×2 -matrix with eigenvalues 1 and 0. Representing $F(x)$ as a linear combination of the identity matrix and the three Pauli matrices $\vec{\sigma}$ defined by

$$\sigma^1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma^3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix},$$

we obtain

$$F(x) = \frac{1}{2}(\mathbf{1} + \vec{v}_x \vec{\sigma}), \quad \text{where } |\vec{v}_x| = 1. \quad (1.14)$$

In this way, every $F(x)$ can be described by a unit vector $\vec{v}_x \in S^2$. The Lagrangian is computed to be

$$\mathcal{L}[A_{xy}] = \frac{1}{8}(1 + \vec{v}_x \cdot \vec{v}_y)^2. \quad (1.15)$$

In particular, all points have timelike separation. Furthermore, the Lagrangian becomes smaller if the angle between \vec{v}_x and \vec{v}_y is larger. Thus qualitatively speaking, our variational principle attempts to maximize the angles between the vectors $(\vec{v}_x)_{x=1, \dots, m}$. In other words, the variational principle tries to distribute m points on the sphere, maximizing their distances according to the “repulsive pair potential” (1.15). This problem has been studied for a variety of potentials; see [16] for a review.

Again, the minimizer cannot be unique, because the action of $U(f)$ will give rise to different minimizers. Furthermore, other minimizers are obtained by permuting the points of M . Even if we consider the problem modulo the action of $U(f)$ on \mathcal{F} and permutations in M , in general the minimizers will still not be unique. Namely, as discussed in [16], the discreteness of the problem will in general give rise to a

complicated geometric structure on the sphere, leading to many minima of the action. \diamond

The following example illustrates that the causal structure can be a further source of non-uniqueness.

Example 1.6. (*Non-uniqueness for point distributions on S^2*) We choose $f = 2$, $\beta \in (0, 1)$ and let $M = \{1, 2\}$ consist of two points, again with the normalized counting measure. Representing the matrices $F(x)$ similar to (1.14) by a linear combination of Pauli matrices,

$$F(x) = \frac{1 - \beta}{2} \mathbf{1} + \frac{1 + \beta}{2} \vec{v}_x \vec{\sigma} \quad \text{with} \quad |\vec{v}_x| = 1, \quad (1.16)$$

a short calculation shows that the points 1 and 2 are spacelike separated if and only if

$$\vec{v}_1 \cdot \vec{v}_2 < \frac{-\beta^2 + 6\beta - 1}{(1 + \beta)^2}.$$

In this case, only the diagonal terms A_{xx} contribute to the action, and thus

$$\mathcal{S} = \frac{1}{4} (\mathcal{L}[A_{11}] + \mathcal{L}[A_{22}]) = \frac{1}{4} (1 - \beta^2)^2. \quad (1.17)$$

Noting that the values of $\mathcal{L}[A_{xx}]$ are already determined by the given parameter β but are independent of the choice of the matrices $F(x) \in \mathcal{F}$, we see that (1.17) is even the infimum of the action. We conclude that there is a continuous family of minimizers. A short calculation shows that the eigenvalues of the matrix A_{12} depend on the angle between \vec{v}_1 and \vec{v}_1 , and thus the minimizers for different values of this angle cannot be $U(f)$ -equivalent. \diamond

We conclude that if the measure μ is the counting measure, we cannot hope for uniqueness, because the discrete nature of the problem will give rise to a complicated geometric structure with many minima of the action. The situation will be similarly involved if μ consist of both discrete and a continuous parts.

However, the above examples give us hope that the uniqueness problem might simplify if the measure μ is purely continuous. Namely, in this case the variational principle with Lagrangian (1.15) should have a unique minimizer, obtained by distributing the continuous measure uniformly on the sphere. One might conjecture that the same measure should also be the minimizer in the case $\beta > 0$. Also, can one expect a unique minimizer in the case $f \geq 2$? Motivated by these specific questions, we now turn attention to a more systematic study of the uniqueness problem in the continuous setting.

1.4. The Continuum Variational Principle and its Hilbert Space Formulation. In the remainder of this chapter we shall assume that μ is a *non-atomic measure* on M (see [10, Section 40] or the proof Lemma 1.4). In this case, we can conveniently reformulate our variational problem purely in terms of positive normalized regular Borel measures on \mathcal{F} , denoted in what follows by $\mathcal{B}(\mathcal{F})$. Namely, suppose that we

$$\text{minimize} \quad \mathcal{S}(\rho) = \iint_{\mathcal{F} \times \mathcal{F}} \mathcal{L}[p \cdot q] d\rho(p) d\rho(q) \quad \text{on } \mathcal{B}(\mathcal{F}). \quad (1.18)$$

Then, since every $F \in \mathbb{M}$ gives rise to a corresponding measure ρ on \mathcal{F} (see (1.6)), it is obvious that $\inf_{\mathcal{F} \in \mathbb{M}} \mathcal{S}[F] \geq \inf_{\rho \in \mathcal{B}(\mathcal{F})} \mathcal{S}(\rho)$. Conversely, the inductive construction in the proof of Lemma 1.4 shows that every $\rho \in \mathcal{B}(\mathcal{F})$ can be realized by a function $F \in \mathbb{M}$,

and that this F is unique up to isomorphisms of the measure space (M, μ) . Hence in what follows it suffices to consider the variational principle (1.18), referred to as the *continuum variational principle*. The existence of minimizers is an immediate consequence of Lemma 1.3.

Corollary 1.7. *The infimum of the continuum variational principle (1.18) is attained.*

In order to get into the position to apply spectral methods, we let $\mathcal{H} = L^2(\mathcal{F}, d\mu_{\mathcal{F}})$ be the Hilbert space with scalar product

$$\langle \psi, \phi \rangle = \int_{\mathcal{F}} \overline{\psi} \phi \, d\mu_{\mathcal{F}}, \quad \psi, \phi \in \mathcal{H}.$$

If we assume that the measure ρ in (1.18) is so regular and bounded that it has a Radon-Nikodym decomposition (see for example [10, Section 31])

$$d\rho = \psi \, d\mu_{\mathcal{F}} \quad \text{with } \psi \in \mathcal{H}, \quad (1.19)$$

then the action can be expressed as an expectation value

$$\mathcal{S}[\rho] = \langle \psi, L\psi \rangle,$$

where L is the integral operator defined by

$$(L\psi)(p) = \int \mathcal{L}[p \cdot q] \psi(q) \, d\mu_{\mathcal{F}}(q). \quad (1.20)$$

The conditions that ρ be positive and normalized can be expressed by demanding that $\psi \geq 0$ and that $\langle \psi, 1_{\mathcal{F}} \rangle = 1$ ($1_{\mathcal{F}}$ again denotes the constant function one). Hence the variational principle (1.18) can be reformulated in Hilbert spaces by

$$\boxed{\text{minimize } \mathcal{S}(\psi) = \langle \psi, L\psi \rangle \text{ for } \psi \in \mathcal{H} \text{ with } \psi \geq 0 \text{ and } \langle \psi, 1_{\mathcal{F}} \rangle = 1.} \quad (1.21)$$

We remark that the constraint $\psi \geq 0$ is unusual in the Hilbert space setting. In particular, (1.21) is much different from minimizing a Rayleigh quotient. Furthermore, we point out that the representation (1.19) poses a strong condition on the Borel measure ρ . However, the measures satisfying this condition are dense in $\mathcal{B}(\mathcal{F})$ in the $C^0(\mathcal{F})^*$ -topology. Therefore, the infima of (1.18) and (1.21) coincide. But it is not clear whether the variational principle (1.21) has a minimizer. In cases where the answer is yes, this means that there are minimizers ρ of (1.18) satisfying (1.19). If every minimizing sequence of (1.21) had a convergent subsequence, we could even conclude that every minimizer ρ of (1.18) satisfies (1.19).

1.5. Non-Uniqueness and Non-Triviality of Minimizers. In this section we shall use spectral methods to prove the following result.

Theorem 1.8. *For the continuum variational principle in the Hilbert space formulation (1.21) the following holds:*

- (i) *In the case $\beta = 0$, the constant function $1_{\mathcal{F}}$ is a minimizer,*

$$\langle 1_{\mathcal{F}}, L1_{\mathcal{F}} \rangle = \inf_{\rho \in \mathcal{B}(\mathcal{F})} \mathcal{S}(\rho).$$

There is an infinite-dimensional family of minimizers.

- (ii) *In the case $0 < \beta < 1$, the function $1_{\mathcal{F}}$ is not a minimizer,*

$$\langle 1_{\mathcal{F}}, L1_{\mathcal{F}} \rangle > \inf_{\rho \in \mathcal{B}(\mathcal{F})} \mathcal{S}(\rho).$$

The minimizer $\rho \in \mathcal{B}(\mathcal{F})$ from Corollary 1.7 is not unique.

Moreover, in the case $\beta = 0$ and $f = 2$, we give an explicit example of a minimizer $\rho \in \mathcal{B}(\mathcal{F})$ which does not have the representation (1.19) with $\psi \in \mathcal{H}$ (see Example 1.11).

In preparation for the proof, we compile a few spectral properties of the operator L .

Lemma 1.9. *L is a compact self-adjoint operator on \mathcal{H} . The eigenvectors corresponding to non-zero eigenvalues are continuous functions on \mathcal{F} . The sup-norm $\|L\|$ is a non-degenerate eigenvalue, and the constant function $1_{\mathcal{F}}$ is the corresponding eigenvector.*

Proof. Clearly, the kernel $\mathcal{L}[pq]$ of L is a continuous function on $\mathcal{F} \times \mathcal{F}$. Using furthermore that \mathcal{F} is a compact manifold, the operator L is obviously bounded. Moreover, the kernel $\mathcal{L}[p \cdot q]$ is real-valued and, as explained after Definition 1.1, it is symmetric in its two arguments. This implies that L is self-adjoint. The integral estimate

$$\mathrm{Tr}(L^*L) = \iint_{\mathcal{F} \times \mathcal{F}} \mathcal{L}[pq] \mathcal{L}[qp] d\mu_{\mathcal{F}}(p) d\mu_{\mathcal{F}}(q) \leq \mu(\mathcal{F})^2 \sup_{p,q} |\mathcal{L}[pq]|^2$$

shows that the operator L is Hilbert-Schmidt, and thus compact. This means that its the spectrum $\sigma(L) \subset \mathbb{R}$ is purely discrete, bounded and accumulates at most at zero. The spectral theorem gives a decomposition

$$L = \sum_{\lambda \in \sigma(L)} \lambda E_{\lambda},$$

where the E_{λ} are projectors onto finite-dimensional, mutually orthogonal eigenspaces.

Suppose that ψ is an eigenvector of L corresponding to an eigenvalue $\lambda \neq 0$. Then ψ can be written as

$$\psi(p) = \frac{1}{\lambda} \int_{\mathcal{F}} \mathcal{L}[pq] \psi(q) d\mu_{\mathcal{F}}(q).$$

Regarding the right side as a convolution of ψ with a continuous kernel, one sees that ψ is a continuous function.

The Lagrangian (1.2) is $U(f)$ -invariant, meaning that $\mathcal{L}[pq] = \mathcal{L}[UpqU^{-1}]$ for every $U \in U(f)$. Using furthermore the $U(f)$ -invariance of the integration measure $d\mu_{\mathcal{F}}$, we obtain

$$(L1_{\mathcal{F}})(p) = \int_{\mathcal{F}} \mathcal{L}[pq] d\mu_{\mathcal{F}}(q) = \int_{\mathcal{F}} \mathcal{L}[pU^{-1}qU] d\mu_{\mathcal{F}}(q) = (L1_{\mathcal{F}})(UpU^{-1}).$$

Since $U(f)$ acts transitively on \mathcal{F} , we conclude that the function $L(1_{\mathcal{F}})$ is constant. Hence $1_{\mathcal{F}}$ is an eigenvector.

The idea for completing the proof is to note that the operator L has a non-negative kernel (cf. (1.20) and (1.2)) and to apply the Perron-Frobenius theorem (see [17, Chapter 5] for matrices and [8, Section 3.3] for integral operators). Unfortunately, this theorem cannot be applied in our setting, because it requires that the kernel be positive almost everywhere, whereas our kernel $L[pq]$ vanishes whenever the points p and q are spacelike separated. But we can adapt the Perron-Frobenius method as follows: First, the estimate

$$-\inf \sigma(L) = \sup_{\phi \in \mathcal{H}, \|\phi\|=1} -\langle \phi, L\phi \rangle \leq \sup_{\phi \in \mathcal{H}, \|\phi\|=1} \langle |\phi|, L|\phi| \rangle \leq \sup \sigma(L)$$

shows that the supremum of the spectrum coincides with the sup-norm. Hence, using that L is compact, $\|L\| > 0$ is an eigenvalue corresponding to a finite-dimensional eigenspace. Suppose that ψ is a corresponding normalized eigenvector. Then

$$\|L\| = \langle \psi, L\psi \rangle \leq \langle |\psi|, L|\psi| \rangle \leq \|L\|,$$

showing that $|\psi|$ is again an eigenvector corresponding to the eigenvalue $\|L\|$. This eigenvector is not orthogonal to $1_{\mathcal{F}}$, because

$$\langle |\phi|, 1_{\mathcal{F}} \rangle = \int_{\mathcal{F}} |\phi| d\mu_{\mathcal{F}} > 0.$$

This implies that the two eigenvectors must be in the same eigenspace, and thus $L 1_{\mathcal{F}} = \|L\| 1_{\mathcal{F}}$.

We now proceed by contradiction. Assume that the eigenvalue $\|L\|$ is degenerate. We choose a vector ψ in the corresponding eigenspace which is orthogonal to $1_{\mathcal{F}}$. Since the real and imaginary parts of an eigenfunction are again eigenvectors, we can arrange that ψ is real-valued. Then the orthogonality $\langle \psi, 1_{\mathcal{F}} \rangle = 0$ implies that ψ changes sign. Since ψ is continuous, its zero set must be non-empty. We choose a point p_0 on the boundary of the zero set. Then $\psi(p_0) = 0$, but ψ is non-trivial on any neighborhood of p_0 . Since the Lagrangian is continuous and $\mathcal{L}[p_0 p_0] > 0$, there is a point q_0 in a neighborhood of p_0 where $\mathcal{L}[p_0 q_0] > 0$ and $\psi(q_0) \neq 0$. Taking the linear combination

$$\phi = 1_{\mathcal{F}} - \frac{2}{\psi(q_0)} \psi,$$

we have constructed an eigenvector corresponding to the eigenvalue $\|L\|$ such that

$$\phi(p_0) = 1, \quad \phi(q_0) = -1 \quad \text{and} \quad \mathcal{L}[p_0 q_0] > 0.$$

Using continuity, it follows that the function $\mathcal{L}[p q] \phi(p) \phi(q)$ is strictly negative on a set of non-zero measure. Hence

$$\begin{aligned} \|L\| \|\phi\|^2 &= \langle \phi, L\phi \rangle = \iint_{\mathcal{F} \times \mathcal{F}} \mathcal{L}[p q] \phi(p) \phi(q) d\mu_{\mathcal{F}}(p) d\mu_{\mathcal{F}}(q) \\ &< \iint_{\mathcal{F} \times \mathcal{F}} \mathcal{L}[p q] |\phi(p)| |\phi(q)| d\mu_{\mathcal{F}}(p) d\mu_{\mathcal{F}}(q) = \langle |\phi|, L|\phi| \rangle, \end{aligned}$$

a contradiction. \square

We can now characterize the structure of the minimizers of the continuum variational principle depending on spectral properties of L . We distinguish between three cases:

(A) $L \geq 0$ and $\ker L = \{0\}$:

We choose an orthonormal eigenvector basis $(\psi_n)_{n \in \mathbb{N}}$ with $L\psi_n = \lambda_n \psi_n$, ordered such that $\psi_1 = 1_{\mathcal{F}}$ and $\lambda_1 = \|L\|$. Expanding the vector ψ in (1.21) in this basis, the condition $\langle \psi, 1_{\mathcal{F}} \rangle = 1$ implies that the coefficient of ψ_1 equals one,

$$\psi = \psi_1 + \sum_{n=2}^{\infty} c_n \psi_n \quad \text{with} \quad \sum_{n=2}^{\infty} |c_n|^2 < \infty. \quad (1.22)$$

Using furthermore that all eigenvalues are strictly positive, we obtain the estimate

$$\langle \psi, L\psi \rangle = \lambda_1 + \sum_{n=2}^{\infty} \lambda_n |c_n|^2 \geq \lambda_1, \quad (1.23)$$

and equality holds only if all the coefficients c_2, c_3, \dots vanish. This shows that the constant function is the unique minimizer.

(B) $L \geq 0$ and the kernel of L is non-trivial:

Again representing ψ in the form (1.22), the inequality (1.23) again holds, but

we have equality if and only if $\psi - \psi_1 \in \ker L$. Since we must take into account the condition $\psi \geq 0$, the set of all minimizers in \mathcal{H} is given by

$$(\psi_1 + \ker L) \cap \{\psi \in \mathcal{H}, \psi \geq 0 \text{ a.e.}\}. \quad (1.24)$$

Thus the constant function is again a minimizer, but there are other, nontrivial minimizers. If the kernel of L is finite-dimensional, the functions in (1.24) are all continuous, and thus we can say that all minimizing measures of the variational principle (1.18) have the representation (1.19) with a continuous function $\psi \in \mathcal{H}$. However, if L is infinite-dimensional, in general there will be sequences in (1.24) which do not converge in \mathcal{H} but do converge in $C^0(\mathcal{F})^*$ to a non-trivial Borel measure. Thus in this case we can expect minimizers of (1.18) which do not admit a representation (1.19) with $\psi \in \mathcal{H}$ (for an example of such a minimizer see Example 1.11).

(C) L has negative eigenvalues:

The inequality (1.23) can be violated by choosing the coefficient c_n corresponding to one of the negative eigenvalues to be non-zero. Hence the constant function is no longer a minimizer. There seems no general reason why a minimizing sequence should converge in \mathcal{H} . Thus we cannot expect that there are any minimizers in \mathcal{H} . But according to Corollary 1.7, the minimizers will still exist in the sense of measures. Since these minimizers necessarily break the $U(f)$ -symmetry, the action of $U(f)$ (see page 4) will give rise to other minimizers. Hence the minimizer $\rho \in \mathcal{B}(\mathcal{F})$ as obtained from Corollary 1.7 is not unique.

Following these arguments, it remains to analyze the spectrum of L . We begin with the case $\beta = 0$.

Lemma 1.10. *In the case $\beta = 0$, the operator L is non-negative. Its rank is finite and bounded by*

$$\dim L(\mathcal{H}) < f^4.$$

Proof. In the case $\beta = 0$, every $p \in \mathcal{F}$ is a $f \times f$ -matrix of rank one, having the non-trivial eigenvalue one. We denote a normalized eigenvector of p corresponding to the non-trivial eigenvalue by $u(p) \in \mathbb{C}^f$. Since the matrix pq has rank at most one, the Lagrangian (1.2) simplifies to

$$\mathcal{L}[pq] = \frac{1}{2} |\langle u(p), u(q) \rangle_{\mathbb{C}^f}|^4. \quad (1.25)$$

We now introduce the operator $K : \mathcal{H} \rightarrow \mathbb{C}^f \otimes \mathbb{C}^f \otimes (\mathbb{C}^f)^* \otimes (\mathbb{C}^f)^*$ by

$$K(\psi) = \int_{\mathcal{F}} \psi(p) u(p) \otimes u(p) \otimes u(p)^* \otimes u(p)^* d\mu_{\mathcal{F}}(p)$$

(where we use the natural embedding of \mathbb{C}^f to its dual space given by complex conjugation). Then

$$\begin{aligned} \|K(\psi)\|^2 &= \iint_{\mathcal{F} \times \mathcal{F}} \overline{\psi(p)} \psi(q) \langle u(p), u(q) \rangle_{\mathbb{C}^f}^2 \overline{\langle u(p), u(q) \rangle_{\mathbb{C}^f}} d\mu_{\mathcal{F}}(p) d\mu_{\mathcal{F}}(q) \\ &\stackrel{(1.25)}{=} 2 \langle \psi, L\psi \rangle_{\mathcal{H}}. \end{aligned}$$

In other words, $2L = K^*K$, showing that L is non-negative and that its rank is at most the dimension of the vector space $\mathbb{C}^f \otimes \mathbb{C}^f \otimes (\mathbb{C}^f)^* \otimes (\mathbb{C}^f)^*$. \square

We next give a more explicit analysis of the case $f = 2$ and $\beta = 0$. In this case, the Pauli representation (1.14) allows us to identify \mathcal{F} with S^2 . Then L is a spherically symmetric operator on $L^2(S^2)$. Thus it has the same eigenspaces as the spherical Laplacian,

$$L = \sum_{l=0}^{\infty} \lambda_l E_l,$$

where the E_l are the projection operators onto the eigenspaces of the spherical Laplacian corresponding to the eigenvalue $l(l+1)$. The kernel of the E_l can be given in terms of the spherical harmonics Y_l^m by

$$E_l(p, q) = 4\pi \sum_{m=-l}^l Y_l^m(p) \overline{Y_l^m(q)}, \quad \text{where } p, q \in S^2$$

(the factor 4π arises because our integration measure $\mu_{\mathcal{F}}$ on S^2 has total volume one). The eigenvalues λ_l are most easily computed by applying L to the spherical harmonic Y_l^0 ,

$$\lambda_l Y_l^0(p) = (L Y_l^0)(p) = \int_{\mathcal{F}} \mathcal{L}[p q] Y_l^0(q) d\mu_{\mathcal{F}}(q). \quad (1.26)$$

Choosing on S^2 standard polar coordinates (ϑ, φ) , the spherical harmonics Y_l^0 are multiples of the Legendre polynomials $P_l(\cos \vartheta)$. More precisely, using the standard normalization conventions

$$Y_l^0(\vartheta, \varphi) = \sqrt{\frac{2l+1}{4\pi}} P_l(\cos \vartheta) \quad \text{and} \quad P_l(1) = 1,$$

we can evaluate (1.26) for p at the north pole $\vartheta = 0$ to obtain the simple formula

$$\lambda_l = \frac{1}{2} \int_{-1}^1 \mathcal{L}(\cos \vartheta) P_l(\cos \vartheta) d \cos \vartheta. \quad (1.27)$$

Setting $\beta = 0$, the Lagrangian simplifies to (1.15),

$$\mathcal{L}(\cos \vartheta) = \frac{1}{8} (1 + \cos \vartheta)^2 \quad (\text{if } f = 2, \beta = 0).$$

In this case, the integral (1.27) can easily be calculated

$$\lambda_0 = \frac{1}{6}, \quad \lambda_1 = \frac{1}{12}, \quad \lambda_2 = \frac{1}{60}, \quad \lambda_3 = \lambda_4 = \dots = 0.$$

Counting the multiplicities $2l+1$ of the eigenspaces, the rank of L is computed to be $1 + 3 + 5 = 9$, in agreement with the upper bound $f^4 = 16$ from Lemma 1.10.

This detailed information allows us to give a minimizer which is not in \mathcal{H} .

Example 1.11. (*A distributional minimizer*) In the case $f = 2$ and $\beta = 0$, we again use the identification $\mathcal{F} \simeq S^2$ and choose polar coordinates (ϑ, φ) . For any parameter $a \in [0, 1]$, we define the measure $\rho \in \mathcal{B}(\mathcal{F})$ by

$$\begin{aligned} \int_{\mathcal{F}} g d\rho &= \int_{\mathcal{F}} \left[a + \frac{1-a}{2} \Theta\left(|\cos \vartheta| - \frac{1}{2}\right) \right] g d\mu_{\mathcal{F}} \\ &\quad + \frac{3}{8} (1-a) \frac{1}{2\pi} \int_0^{2\pi} \left[g\left(\cos \vartheta = \frac{1}{2}, \varphi\right) + g\left(\cos \vartheta = -\frac{1}{2}, \varphi\right) \right] d\varphi, \end{aligned}$$

where Θ is the Heaviside function. This is a positive normalized regular Borel measure, but due to the singular contributions at $\cos \vartheta = \pm \frac{1}{2}$, it cannot be represented in the

form (1.19) with $\psi \in \mathcal{H}$. In order to show that ρ is a minimizer, we must verify that it coincides with the constant function on the nontrivial eigenspaces of L , i.e.

$$\rho(Y_0^0) = \frac{1}{\sqrt{4\pi}} \quad \text{and} \quad \rho(Y_l^m) = 0 \quad \text{for all } l = 1, 2 \text{ and } m = -l, \dots, l.$$

The first condition is obvious because $Y_0^0 = (4\pi)^{-\frac{1}{2}}$ is constant and ρ is normalized. Since the spherical harmonics Y_l^m are the restrictions to S^2 of polynomials of degree l in \mathbb{R}^3 , a symmetry consideration in the φ -integral shows that all the other conditions reduce to the three constraints

$$\rho(z) = 0, \quad \rho(3z^2 - 1) = 0, \quad \rho(3x^2 - 1) = 0, \quad (1.28)$$

where (x, y, z) are Cartesian coordinates, where ϑ denotes the angle to the z -axis. The first equation in (1.28) is immediate by symmetry, whereas the second equation follows from the computation

$$\frac{1-a}{4} \int_{\frac{1}{2}}^1 (3z^2 - 1) dz + \frac{3}{8} (1-a) (3z^2 - 1) \Big|_{z=\frac{1}{2}} = 0.$$

In order to verify the third relation, we first note that the symmetry around the z -axis yields $\rho(3x^2 - 1) = \rho(3y^2 - 1)$. Also using the last equation in (1.28), we obtain

$$\rho(3x^2 - 1) = \frac{1}{2} \rho(3(x^2 + y^2 + z^2) - 3) = \frac{1}{2} \rho(3 - 3) = 0,$$

concluding the proof. \diamond

If $\beta > 0$ (and still $f = 2$), the situation is more interesting because of the non-trivial causal structure, which leads to a region where the Lagrangian vanishes identically. Namely, a short calculation using (1.16) yields

$$\mathcal{L}(\cos \vartheta) = \frac{(1 + \beta)^4}{8} (1 + \cos \vartheta) \max\left(0, \cos \vartheta + \frac{1 - 6\beta + \beta^2}{(1 + \beta)^2}\right). \quad (1.29)$$

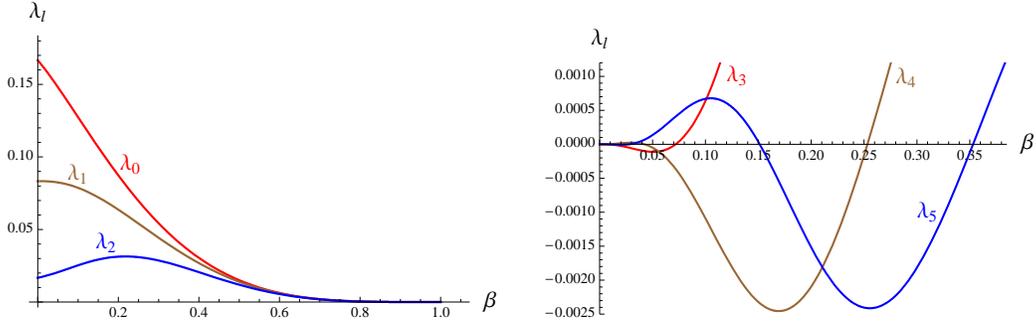
The resulting integrand in (1.27) is again a polynomial in $\cos \vartheta$, and thus for every l , the function $\lambda_l(\beta)$ can be computed in closed form. For example,

$$\lambda_0 = \frac{(1 - \beta)^4(1 + 4\beta + \beta^2)}{6(1 + \beta)^2},$$

and similarly for the other eigenvalues (clearly, the formulas get more complicated for larger l , but expressions up to $l \approx 20$ are handled easily by computer algebra). On the left of Figure 1 the three lowest eigenvalues λ_0 , λ_1 and λ_2 of L are shown as functions of β . These eigenvalues are always positive. On the right of Figure 1, the next eigenvalues λ_3 , λ_4 and λ_5 are plotted versus β . The Taylor expansion

$$\lambda_3 = -\frac{16}{3} \beta^3 + \mathcal{O}(\beta^4)$$

shows that λ_3 is negative for small positive β , and Figure 1 illustrates that this function $\lambda_3(\beta)$ stays negative on the interval $0 < \beta < 0.07$. Thus for β in this range, we are in case (C) on page 12 where the minimizer is non-trivial. If β is further increased, λ_3 becomes positive, but then λ_4 is negative. If β is further increased, λ_4 becomes positive, but then λ_5 is negative. More generally, these plots suggest that for every β in the range $0 < \beta < 1$ at least one of the λ_l should be negative. This is indeed the case, as the following lemma shows.

FIGURE 1. The eigenvalues $\lambda_l(\beta)$ of the operator L in the case $f = 2$.

Lemma 1.12. *In the case $f = 2$,*

$$\min_{l \in \mathbb{N}_0} \lambda_l(\beta) < 0 \quad \text{for all } \beta \in (0, 1) .$$

Proof. In order to analyze the asymptotics $\beta \nearrow 1$, we first expand the second fraction in (1.29),

$$\frac{1 - 6\beta + \beta^2}{(1 + \beta)^2} = -1 + \frac{1}{2} (1 - \beta)^2 + \mathcal{O}((1 - \beta)^3) ,$$

showing that the Lagrangian vanishes identically except in a neighborhood of the north pole $\vartheta = 0$. Thus we may also expand in powers of ϑ to obtain the asymptotic Lagrangian

$$\mathcal{L}^{\text{asy}}(\vartheta) = \frac{(1 + \beta)^4}{8} \left(1 - \frac{\vartheta^2}{4} \right) \max\left(0, \frac{4(1 - \beta)^2}{(1 + \beta)^2} - \vartheta^2 \right) . \quad (1.30)$$

In order to derive the asymptotic form of the Legendre polynomials $P_l(\cos \vartheta)$ near the pole, we note that these polynomials are given as solutions of the ODE

$$-\frac{1}{\sin \vartheta} \frac{d}{d\vartheta} \left(\sin \vartheta \frac{d}{d\vartheta} P_l(\cos \vartheta) \right) = l(l + 1) P_l(\cos \vartheta) , \quad P_l(1) = 1 .$$

Using the asymptotics $\sin \vartheta = \vartheta + \mathcal{O}(\vartheta^3)$, this differential equation simplifies to

$$-\left(\frac{d^2}{d\vartheta^2} + \frac{1}{\vartheta} \frac{d}{d\vartheta} \right) P_l^{\text{asy}}(\vartheta) = l(l + 1) P_l^{\text{asy}}(\vartheta) , \quad P_l^{\text{asy}}(0) = 1 ,$$

whose solution is a Bessel function of the first kind,

$$P_l^{\text{asy}}(\vartheta) = J_0\left(\sqrt{l(l + 1)} \vartheta\right) . \quad (1.31)$$

Substituting (1.30) and (1.31) into (1.27) and using the asymptotic form of the integration measure $d \cos \vartheta = (\vartheta + \mathcal{O}(\vartheta^3)) d\vartheta$, the integral can be computed in terms of the confluent hypergeometric function,

$$\lambda_l^{\text{asy}} = \frac{1}{2} \int_0^\pi \mathcal{L}^{\text{asy}}(\vartheta) P_l^{\text{asy}}(\vartheta) \vartheta d\vartheta \quad (1.32)$$

$$= \frac{(1 - \beta)^2}{\lambda} \left((1 + \beta(2 + \beta + \lambda)) {}_0F_1(3, -x) - (1 - \beta)^2 {}_0F_1(2, -x) \right) , \quad (1.33)$$

where we set

$$\lambda = l(l + 1) \quad \text{and} \quad x = \frac{(1 - \beta)^2}{(1 + \beta)^2} \lambda . \quad (1.34)$$

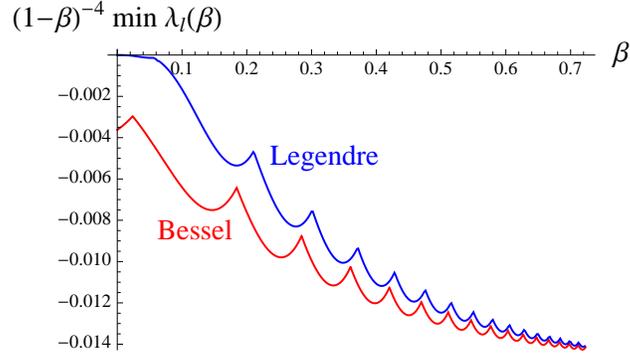


FIGURE 2. The smallest eigenvalue of L in the case $f = 2$ using the exact formulas with Legendre polynomials and the asymptotics with Bessel functions.

Next we need to specify l as a function of β . Qualitatively, speaking, the Bessel function (1.31) oscillates with frequency of the order $\sqrt{l(l+1)}$, whereas the Lagrangian (1.30) decreases in ϑ , vanishing identically for

$$\vartheta \geq \vartheta_{\max} := 2 \frac{1-\beta}{1+\beta}.$$

Thus in order to make the integral (1.32) negative, we choose l such that $P_l^{\text{asy}}(\vartheta)$ oscillates on $[0, \vartheta_{\max}]$ just once, being negative at $\vartheta = \vartheta_{\max}$. A good method would be to determine l from the equation

$$\sqrt{l_{\text{asy}}(l_{\text{asy}} + 1)} \vartheta_{\max} = 5.5.$$

Since this is in general not an integer, we introduce l using the Gauss bracket,

$$l(\beta) := 1 + [l_{\text{asy}}].$$

With this choice of l , a simple calculation shows that if $\beta \in [0.4, 1)$, the variable x as defined by (1.34) takes values in the range $x \in [7, 12]$. For β and x chosen in these intervals, a direct inspection shows that the function (1.33) is always negative.

Our analysis so far shows that the lemma holds if β is sufficiently close to one. On the other hand, on any interval $\beta \in (0, \beta_{\max}]$ with $\beta_{\max} < 1$, one can consider the explicit formulas obtained from the Legendre polynomials to verify that L has a negative eigenvalue. As shown in Figure 2, at $\beta \approx 0.7$ the asymptotics with Bessel functions is a good approximation to the exact analysis. Because of this obvious fit, we omit rigorous error estimates of the asymptotic analysis. \square

The case $f > 2$ is considerably more complicated. However, as shown in the next lemma, there is a general mechanism giving rise to negative eigenvalues.

Lemma 1.13. *If $f > 2$ and $0 < \beta < 1$, the operator L has negative eigenvalues.*

Proof. We choose $p, q \in \mathcal{F}$ having the matrix representation

$$p = P_{e_1} - \beta P_{e_2}, \quad q = P_{e_1} - \beta P_{e_3},$$

where P_{e_i} denotes the orthogonal projection to the canonical basis vector $e_i \in \mathbb{C}^f$. It suffices to show that the 2×2 -matrix

$$l := \begin{pmatrix} \mathcal{L}[pp] & \mathcal{L}[pq] \\ \mathcal{L}[qp] & \mathcal{L}[qq] \end{pmatrix} \quad (1.35)$$

has a negative eigenvalue, as the following argument shows. Suppose that $\phi \in \mathbb{C}^2$ is a vector with $\langle \phi, l\phi \rangle_{\mathbb{C}^2} < 0$. We consider a series $\psi_n \in \mathcal{H}$ which converges in the $C^0(\mathcal{F})^*$ -topology to the measure $\phi_1\delta_p + \phi_2\delta_q$ (where δ_p denotes the Dirac measure supported at p). Then

$$\langle \psi_n, L\psi_n \rangle_{\mathcal{H}} \xrightarrow{n \rightarrow \infty} \langle \phi, l\phi \rangle_{\mathbb{C}^2} < 0,$$

proving that L has indeed negative eigenvalues.

To show that the matrix (1.35) has a negative eigenvalue, we first compute the spectra of the matrix products,

$$\sigma(pp) = \sigma(qq) = \{1, \beta^2, 0\}, \quad \sigma(pq) = \sigma(qp) = \{1, 0\}.$$

Hence

$$l = \frac{1}{2} \begin{pmatrix} (1 - \beta^2)^2 & 1 \\ 1 & (1 - \beta^2)^2 \end{pmatrix}, \quad \det l = \frac{1}{4} ((1 - \beta^2)^4 - 1) < 0,$$

and thus l has precisely one negative eigenvalue. \square

This completes the proof of Theorem 1.8.

We now turn attention to a more general class of variational principles. The main additional difficulty will be that the target space is no longer compact. Intuitively, this leads to the possibility that part of the support of the measures ρ_k “escapes to infinity.” In order to rule this out, we must control the behavior of the measures ρ_k by suitable a-priori estimates.

2. A GENERAL CLASS OF CAUSAL VARIATIONAL PRINCIPLES

2.1. Definitions and Statement of Results. Let (M, μ) be a measure space of total volume $\mu(M) = 1$. For given integers f, n with $f \geq 2n$ we let \mathcal{F} be the set of all Hermitian $f \times f$ -matrices of rank at most $2n$, having at most n positive and at most n negative eigenvalues. We let \mathbb{M} be the set of matrix-valued functions

$$\mathbb{M} = \{F : M \rightarrow \mathcal{F} \text{ measurable}\}.$$

For a given $F \in \mathbb{M}$ and any $x, y \in M$, we again form the matrix product (1.1) and denote its eigenvalues counted with algebraic multiplicities by

$$\lambda_1^{xy}, \dots, \lambda_{2n}^{xy}, \underbrace{0, \dots, 0}_{f - 2n \text{ times}} \quad \text{with } \lambda_j^{xy} \in \mathbb{C}. \quad (2.1)$$

We define the *spectral weight* $|A_{xy}|$ by

$$|A_{xy}| = \sum_{j=1}^{2n} |\lambda_j^{xy}|, \quad (2.2)$$

and similarly set $|A_{xy}^2| = \sum_{j=1}^{2n} |\lambda_j^{xy}|^2$. We introduce

$$\boxed{\text{the Lagrangian} \quad \mathcal{L}[A_{xy}] = |A_{xy}^2| - \frac{1}{2n} |A_{xy}|^2} \quad (2.3)$$

and define the functionals \mathcal{S} and \mathcal{T} by

$$\mathcal{S}[F] = \iint_{M \times M} \mathcal{L}[A_{xy}] d\mu(x) d\mu(y) \quad (2.4)$$

$$\mathcal{T}[F] = \iint_{M \times M} |A_{xy}|^2 d\mu(x) d\mu(y). \quad (2.5)$$

We also introduce the following constraints:

(C1) The **trace constraint**:

$$\int_M \text{Tr}(F(x)) d\mu(x) = f.$$

(C2) The **identity constraint**:

$$\int_M F(x) d\mu(x) = \mathbf{1}_{\mathbb{C}^f}.$$

(C3) **Prescribing $2n$ eigenvalues**: We denote the eigenvalues of $F(x)$ counted with multiplicities by ν_1, \dots, ν_f and order them such that

$$\nu_1 \leq \dots \leq \nu_n \leq 0 \leq \nu_{n+1} \leq \dots \leq \nu_{2n} \quad (2.6)$$

and $\nu_{2n+1} = \dots = \nu_f = 0$. We introduce constants c_1, \dots, c_{2n} and impose that

$$\nu_j(x) = c_j \quad \text{for all } x \in M \text{ and } j \in K. \quad (2.7)$$

We now state our results and explain them afterwards. In order to rule out trivial cases, we shall always assume that the set of functions satisfying the constraints is non-empty.

Theorem 2.1. *Imposing the constraint (C3) and in addition possibly the constraints (C1) or (C2), the variational principle*

$$\text{minimize } \mathcal{S}[F] \text{ on } \mathbb{M}$$

attains its minimum.

Theorem 2.2. *For any parameter ν with*

$$\nu > -\frac{2n}{2n-1}, \quad (2.8)$$

we consider the variational principle

$$\text{minimize } \mathcal{T}[F] + \nu \mathcal{S}[F] \text{ on } \mathbb{M}, \quad (2.9)$$

possibly with the additional constraints (C1) or (C2). Then the minimum is attained by a function $F \in L^2(M, \mathcal{F}, d\mu)$.

Theorem 2.3. *For any parameter $C > 0$, we consider the variational principle*

$$\text{minimize } \mathcal{S}[F] \text{ on } \mathbb{M}_C := \{F \in \mathbb{M} \text{ with } \mathcal{T}[F] \leq C\},$$

possibly with the additional constraints (C1) or (C2). Then the minimum is attained by a function $F \in L^2(M, \mathcal{F}, d\mu)$.

Before coming to the proofs, we briefly discuss the variational principles and our results. First of all, labeling the eigenvalues as in (2.1), the Lagrangian (2.3) can be written as

$$\mathcal{L}[A_{xy}] = \frac{1}{4n} \sum_{i,j=1}^{2n} \left(|\lambda_i^{xy}| - |\lambda_j^{xy}| \right)^2. \quad (2.10)$$

In particular, one sees that the Lagrangian is always non-negative. Furthermore, the Lagrangian is causal in the sense that it vanishes identically for spacelike separation defined as follows.

Definition 2.4. (causal structure) *Two space-time points $x, y \in M$ are called **time-like** separated if the λ_j^{xy} are all real. They are said to be **spacelike** separated if all the λ_j^{xy} , $j = 1, \dots, 2n$ form complex conjugate pairs and all have the same absolute value. In all other cases, the points x and y are said to be **lightlike** separated.*

Theorem 2.1 is an obvious generalization of Theorem 1.2. Theorems 2.2 and 2.3 are more interesting because the range of the admissible functions F is in general a non-compact subset of \mathcal{F} . The constraints (C1), (C2) and/or (C3) are needed in order to rule out the trivial minimizer $F \equiv 0$. Clearly, (C2) implies (C1). To explain the assumptions of Theorem 2.2, we note that the inequality

$$|A_{xy}^2| = \sum_{j=1}^{2n} |\lambda_j^{xy}|^2 \leq \left(\sum_{j=1}^{2n} |\lambda_j^{xy}| \right)^2 = |A_{xy}|^2$$

yields the following upper bound for the Lagrangian (2.3),

$$\mathcal{L}[A_{xy}] \leq \left(1 - \frac{1}{2n} \right) |A_{xy}|^2. \quad (2.11)$$

Thus the condition (2.8) ensures that the functional $\mathcal{T}[F] + \nu \mathcal{S}[F]$ in Theorem 2.2 is non-negative. If $\nu < -\frac{2n}{2n-1}$, this functional is unbounded from below, as the following example shows.

Example 2.5. (Ill-posedness) We consider the case $n = 1$ and $f = 2$, and choose $M = \{1, \dots, 4\}$ with the normalized counting measure $\mu(\{l\}) = \frac{1}{4}$ for all $l \in M$. For any $k \geq 0$ we define $F \in \mathbb{M}$ by

$$\begin{aligned} F(1) &= \begin{pmatrix} k+4 & 0 \\ 0 & 0 \end{pmatrix}, & F(2) &= \begin{pmatrix} 0 & 0 \\ 0 & k+4 \end{pmatrix}, \\ F(3) &= \begin{pmatrix} -k & 0 \\ 0 & 0 \end{pmatrix}, & F(4) &= \begin{pmatrix} 0 & 0 \\ 0 & -k \end{pmatrix}. \end{aligned}$$

Then the identity constraint (C2) is satisfied. Moreover, since the matrices A_{xy} are all of rank at most one, we know that $|A_{xy}^2| = |A_{xy}|^2$. Thus

$$\mathcal{T}[F] + \nu \mathcal{S}[F] = \frac{1}{16} \left(1 + \nu \frac{2n-1}{2n} \right) \sum_{x,y \in M} |A_{xy}|^2.$$

In the case $\nu < -\frac{2n}{2n-1}$, the bracket is negative, and thus the functional tends to minus infinity as $k \rightarrow \infty$. Hence the variational principle (2.9) is ill-posed. \diamond

The remaining border case $\nu = -\frac{2n}{2n-1}$ will not be considered in this paper.

To explain Theorem 2.3, we first note that according to (2.10), the action \mathcal{S} in Theorem 2.3 is non-negative. As will be explained in the next Section 2.2, the constraint $\mathcal{T}[F] \leq C$ is needed, because without an a-priori bound on \mathcal{T} there are examples of divergent minimizing sequences. We also point out that we cannot prove Theorem 2.3 with the alternative constraint $\mathcal{T}[F] = C$. This is because when taking the limit of a minimizing sequence $F_k \rightarrow F$, the functional \mathcal{T} need not converge, and indeed we can only prove that $\mathcal{T}[F] < \lim_{k \rightarrow \infty} \mathcal{T}[F_k]$. This so-called ‘‘bubbling phenomenon’’ will be explained in Section 2.3. The proofs of Theorems 2.1–2.3 will be completed in Section 2.4.

2.2. Counter Examples to Compactness. We now illustrate in simple counter examples why the constraint $\mathcal{T}[F] \leq C$ in Theorem 2.3 is needed. In the first three examples, the action $\mathcal{S}[F]$ is uniformly bounded for a divergent family of functions F . In the last example, we construct an unbounded series of functions $F_k : M \rightarrow \mathcal{F}$ which is even a minimizing sequence because $\mathcal{S}[F_k] \rightarrow 0$. In all these examples we satisfy the identity constraint (C2).

Example 2.6. (*Divergent series with bounded action*) We let $n = 1$, $f = 2$ and $M = \{1, \dots, 4\}$ with the normalized counting measure. For any given parameter $\tau \in \mathbb{R}$ we choose the function $F : M \rightarrow \mathcal{F}$ by

$$F(1) = \begin{pmatrix} 4 & 0 \\ 0 & 0 \end{pmatrix}, \quad F(2) = \begin{pmatrix} 0 & 0 \\ 0 & 4 \end{pmatrix}, \quad F(3) = -F(4) = \tau \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

Obviously, these matrices all have at most one positive and one negative eigenvalue. Furthermore, the identity constraint (C2) is satisfied. Using that the matrices $F(1)$ and $F(2)$ are of rank one, we find

$$\mathcal{L}[A_{11}] = \frac{1}{2} |A_{11}|^2 = 128 = \mathcal{L}[A_{22}], \quad \mathcal{L}[A_{12}] = 0.$$

Since the square of the matrix $F(3)$ is the identity, we obtain $\mathcal{L}[A_{33}] = 0$, and similarly $\mathcal{L}[A_{44}] = \mathcal{L}[A_{34}] = 0$. The matrix $F(1)F(3)$ is nilpotent and thus $\mathcal{L}[A_{13}] = 0$. Similarly, we find that $\mathcal{L}[A_{23}] = \mathcal{L}[A_{24}] = \mathcal{L}[A_{34}] = 0$. We conclude that

$$\mathcal{S}[F] = \frac{1}{16} (\mathcal{L}[A_{11}] + \mathcal{L}[A_{22}]) = 16.$$

Hence the action is bounded uniformly in the parameter τ , but the matrices $F(3)$ and $F(4)$ diverge as $\tau \rightarrow \infty$. \diamond

This example suggests that the compactness problem could be removed simply by setting the divergent matrices equal to zero. The next example shows that this simple procedure does not work, because then the limiting configuration would in general violate the constraints.

Example 2.7. (*Violation of the identity constraint*) We let $n = 1$, $f = 2$ and $M = \{1, \dots, 3\}$ with the normalized counting measure. For a given parameter $\tau > 1$ we choose the function $F : M \rightarrow \mathcal{F}$ as the following linear combinations of Pauli matrices:

$$F(1) = 3 \frac{\sqrt{1+\tau^2}}{\tau} \sigma^3 + 3\mathbb{1}, \quad F(2), F(3) = -\frac{3}{2} \frac{\sqrt{1+\tau^2}}{\tau} \sigma^3 \pm \frac{3}{2} \sqrt{1+\tau^2} \sigma^2.$$

A short calculation shows that these matrices all have at most one positive and one negative eigenvalue. Furthermore, the identity constraint (C2) is satisfied. To compute the action, we first note that

$$F(1)^2 = 9 \frac{1 + 2\tau^2}{\tau^2} \mathbf{1} + 2 \cdot 9 \frac{\sqrt{1 + \tau^2}}{\tau} \sigma^3 \quad \text{and thus} \quad \mathcal{L}[A_{11}] = 2^3 \cdot 9^2 \frac{1 + \tau^2}{\tau^2}.$$

Since the squares of the matrices $F(2)$ and $F(3)$ are multiples of the identity, we find that $\mathcal{L}[A_{22}] = \mathcal{L}[A_{33}] = 0$. Moreover, using the identity for Pauli matrices

$$\sigma^i \sigma^j = \delta^{ij} + i\epsilon^{ijk} \sigma^k, \quad (2.12)$$

we obtain

$$A_{12} = c \mathbf{1} - \frac{9}{2} \frac{\sqrt{1 + \tau^2}}{\tau} \sigma^3 + \frac{9}{2} \sqrt{1 + \tau^2} \sigma^2 - \frac{9i}{2} \frac{1 + \tau^2}{\tau} \sigma^1$$

with $c \in \mathbb{R}$. A short calculation using the anti-commutation relations for the Pauli matrices yields $(A_{12} - c)^2 = 0$, and thus the matrix A_{12} has the eigenvalue c , with algebraic multiplicity two. Using the notion of Definition 2.4, the points 1 and 2 have spacelike separation, so that $\mathcal{L}[A_{12}] = 0$. Similarly one verifies that $\mathcal{L}[A_{13}] = \mathcal{L}[A_{23}] = 0$. We conclude that

$$\mathcal{S}[F] = \frac{1}{9} \mathcal{L}[A_{11}] = 72 \frac{1 + \tau^2}{\tau^2}.$$

Hence in this example the action is bounded uniformly in τ , although the matrices $F(2)$ and $F(3)$ diverge as $\tau \rightarrow \infty$. Setting these two matrices to zero, the remaining matrix $F(1)$ does converge,

$$\lim_{\tau \rightarrow \infty} F(1) = 3(\sigma^3 + \mathbf{1}),$$

but the limiting system no longer satisfies the identity constraint (C2). \diamond

Example 2.8. (*The two-dimensional Dirac sphere*) We let $M = S^2 \subset \mathbb{R}^3$ with $d\mu$ the surface area measure, normalized such that $\mu(S^2) = 1$. Furthermore, we choose $n = 1$ and $f = 2$. For a given parameter $\tau > 1$ we introduce the mapping $F : M \rightarrow \mathcal{F}$ by

$$F(\vec{x}) = \tau \vec{x} \vec{\sigma} + \mathbf{1}. \quad (2.13)$$

Then $\sigma(F(x)) = \{1 + \tau, 1 - \tau\}$, and thus $F(x)$ has one positive and one negative eigenvalue. Furthermore, a symmetry argument shows that the identity constraint (C2) is satisfied. Using the Pauli identities (2.12), one obtains

$$F(\vec{x}) F(\vec{y}) = (1 + \tau^2 \vec{x} \vec{y}) \mathbf{1} + \tau (\vec{x} + \vec{y}) \vec{\sigma} + i\tau^2 (\vec{x} \wedge \vec{y}) \vec{\sigma}.$$

A straightforward calculation yields for the eigenvalues of this matrix

$$\lambda_{1/2} = 1 + \tau^2 \cos \vartheta \pm \tau \sqrt{1 + \cos \vartheta} \sqrt{2 - \tau^2 (1 - \cos \vartheta)}, \quad (2.14)$$

where ϑ denotes the angle ϑ between \vec{x} and \vec{y} . If ϑ is sufficiently small, the term $(1 - \cos \vartheta)$ is close to zero, and thus the arguments of the square roots are all positive. However, if ϑ becomes so large that

$$\vartheta \geq \vartheta_{\max} := \arccos\left(1 - \frac{2}{\tau^2}\right),$$

the argument of the last square root in (2.14) becomes negative, so that the $\lambda_{1/2}$ form a complex conjugate pair. The calculation

$$\lambda_1 \lambda_2 = \det(F(\vec{x}) F(\vec{y})) = \det(F(\vec{x})) \det(F(\vec{y})) = (1 + \tau)^2 (1 - \tau)^2 > 0$$

shows that if the $\lambda_{1/2}$ are both real, then they have the same sign. Hence the Lagrangian simplifies to

$$\begin{aligned}\mathcal{L}[A_{xy}] &= \mathcal{L}(\cos \vartheta) = \frac{(\lambda_1 - \lambda_2)^2}{2} \Theta(\vartheta_{\max} - \vartheta) \\ &= 2\tau^2 (1 + \cos \tau) (2 - \tau^2 (1 - \cos \vartheta)) \Theta(\vartheta_{\max} - \vartheta).\end{aligned}$$

Using this formula in (2.4), we can carry out the integrals to obtain

$$\mathcal{S}[F] = \frac{1}{2} \int_0^{\vartheta_{\max}} \mathcal{L}(\cos \vartheta) \sin \vartheta \, d\vartheta = 4 - \frac{4}{3\tau^2}. \quad (2.15)$$

Similarly, the functional \mathcal{T} can be computed to be

$$\mathcal{T}[F] = 4\tau^2(\tau^2 - 2) + 12 - \frac{8}{3\tau^2}. \quad (2.16)$$

Hence the action (2.15) is bounded uniformly in τ , although the function F , (2.13), as well as the functional \mathcal{T} , (2.16), diverge as $\tau \rightarrow \infty$. \diamond

We remark that this example can be extended to the case of general even f by decomposing \mathbb{C}^f as a direct sum of $f/2$ copies of \mathbb{C}^2 , choosing $M = S^2 \times \{1, \dots, f/2\}$ and setting

$$F : S^2 \times \{1, \dots, f/2\} \rightarrow (C^2)^{\frac{f}{2}} : (\vec{x}, i) \mapsto 0 \oplus \dots \oplus 0 \oplus \underbrace{(\tau \vec{x} \vec{\sigma} + \mathbf{1})}_{i^{\text{th}} \text{ summand}} \oplus 0 \oplus \dots \oplus 0. \quad (2.17)$$

Example 2.9. (*The three-dimensional Dirac sphere*) This example can be regarded as an analog of Example 2.8, but in one dimension higher. We introduce the four 4×4 -matrices

$$\gamma^\alpha = \begin{pmatrix} \sigma^\alpha & 0 \\ 0 & -\sigma^\alpha \end{pmatrix}, \quad \alpha = 1, 2, 3 \quad \text{and} \quad \gamma^4 = \begin{pmatrix} 0 & \mathbf{1} \\ \mathbf{1} & 0 \end{pmatrix}.$$

These are the Dirac matrices of Euclidean \mathbb{R}^4 , satisfying the anti-commutation relations

$$\{\gamma^i, \gamma^j\} = 2\delta^{ij} \mathbf{1} \quad (i, j = 1, \dots, 4).$$

As is verified either by direct computation or by applying the general theory of Clifford representations, the Dirac matrices are $\text{SO}(4)$ -invariant in the sense that for every rotation $R \in \text{SO}(4)$, there is a unitary matrix $U \in \text{SU}(4)$ such that

$$U\gamma^j U^{-1} = R_k^j \gamma^k. \quad (2.18)$$

We let $f = 4$, $n = 2$ and set $M = S^3$. We introduce the mapping $F : M \rightarrow \mathcal{F}$ by

$$F(x) = \sum_{i=1}^4 \tau x^i \gamma^i + \mathbf{1}.$$

These matrices are $\text{SO}(4)$ -invariant in the sense that

$$F(Rx) = UF(x)U^{-1},$$

where R and U are the transformations in (2.18). Since the unitary transformation U does not affect the eigenvalues of A_{xy} , we see that $\mathcal{L}[A_{xy}] = \mathcal{L}[A_{Rx Ry}]$. Thus the Lagrangian will depend only on the angle ϑ between the vectors x and y . Furthermore, it suffices to compute the Lagrangian for vectors x and y for which the zero component vanishes. But in this case, the eigenvalues of A_{xy} are calculated exactly as

in Example 2.8 above. Thus the eigenvalues are again given by (2.14), but now each eigenvalue appears with algebraic multiplicity two. We conclude that

$$\begin{aligned}\mathcal{L}[A_{xy}] &= \mathcal{L}(\cos \vartheta) = (\lambda_1 - \lambda_2)^2 \Theta(\vartheta_{\max} - \vartheta) \\ &= 4\tau^2 (1 + \cos \tau) (2 - \tau^2 (1 - \cos \vartheta)) \Theta(\vartheta_{\max} - \vartheta).\end{aligned}$$

Inserting this Lagrangian in (2.4),

$$\mathcal{S}[F] = \frac{2}{\pi} \int_0^{\vartheta_{\max}} \mathcal{L}(\cos \vartheta) \sin^2 \vartheta \, d\vartheta,$$

we obtain the same integral as in (2.15), except that the integrand contains an additional factor $\sin \vartheta$. Due to this extra factor, the action decays for large τ ,

$$\mathcal{S}[F] = \frac{512}{15\pi} \frac{1}{\tau} + \mathcal{O}(\tau^{-2}).$$

Thus setting $F_k = F|_{\tau=k}$, we have constructed a divergent minimizing sequence. \diamond

We finally remark that this example generalizes similar to (2.17) to larger f , provided that f is divisible by four.

2.3. The Moment Measures and the Possibility of Bubbling. In this section we discuss the main difficulties in proving Theorems 2.2 and 2.3, and we will explain the methods for resolving these difficulties. The obvious starting point is a minimizing sequence $F_k \in \mathbb{M}$. In the setting of Theorem 2.3, we know that \mathcal{T} is uniformly bounded,

$$\mathcal{T}[F_k] \leq C \quad \text{for all } k \in \mathbb{N}. \quad (2.19)$$

In the setting of Theorem 2.2, the estimate (2.11) shows that (2.19) again holds if we set

$$C = \left[1 + \min(\nu, 0) \left(1 - \frac{1}{2n} \right) \right]^{-1} \max_{k \in \mathbb{N}} (\mathcal{T}[F_k] + \nu \mathcal{S}[F_k]) < \infty.$$

In view of the freedom to act by isomorphisms of the measure space (M, μ) discussed after (1.4), it is preferable to work again instead of the mapping F with the corresponding measure ρ on \mathcal{F} as defined by (1.6). Similar to (1.7), we can write the functionals \mathcal{S} and \mathcal{T} in terms of ρ ,

$$\mathcal{S}(\rho) = \iint_{\mathcal{F} \times \mathcal{F}} \mathcal{L}[p q] \, d\rho(p) \, d\rho(q), \quad \mathcal{T}(\rho) = \iint_{\mathcal{F} \times \mathcal{F}} |p q|^2 \, d\rho(p) \, d\rho(q). \quad (2.20)$$

Moreover, the identity

$$\int_M F(x) \, d\mu(x) = \int_{\mathcal{F}} p \, d\rho(p) \quad (2.21)$$

allows us to also express the constraints (C1) and (C2) in terms of ρ .

The main complication compared to the setting of Chapter 1 is that \mathcal{F} is no longer compact, and thus we need to control the support of the measures ρ_k in order to ensure that the limiting measure $\rho = \lim_{k \rightarrow \infty} \rho_k$ again has total volume one. Moreover, it is no longer obvious that the functionals in (2.20) or the integral (2.21) converge in the limit $k \rightarrow \infty$. At this point, it is helpful to observe that the integrand in (2.21) is homogeneous in p of degree one, whereas the integrands in (2.20) are homogeneous of degree two in both p and q . This allows us to express these functions in terms of so-called moment measures, which we now introduce.

Definition 2.10. Let \mathcal{K} be the compact manifold

$$\mathcal{K} = \{p \in \mathcal{F} \text{ with } \|p\| = 1\} \cup \{0\}.$$

For a given measure ρ on \mathcal{F} we define the measurable sets of \mathcal{K} by the requirement that the sets $\mathbb{R}^+\Omega = \{\lambda p \mid \lambda \in \mathbb{R}^+, p \in \Omega\}$ and $\mathbb{R}^-\Omega$ should be ρ -measurable in \mathcal{F} . We introduce the measures $\mathbf{m}^{(0)}$, $\mathbf{m}^{(1)}$ and $\mathbf{m}^{(2)}$ by

$$\mathbf{m}^{(0)}(\Omega) = \frac{1}{2} \rho(\mathbb{R}\Omega \setminus \{0\}) + \rho(\Omega \cap \{0\}) \quad (2.22)$$

$$\mathbf{m}^{(1)}(\Omega) = \frac{1}{2} \int_{\mathbb{R}^+\Omega} \|p\| d\rho(p) - \frac{1}{2} \int_{\mathbb{R}^-\Omega} \|p\| d\rho(p) \quad (2.23)$$

$$\mathbf{m}^{(2)}(\Omega) = \frac{1}{2} \int_{\mathbb{R}\Omega} \|p\|^2 d\rho(p). \quad (2.24)$$

The measure $\mathbf{m}^{(l)}$ is referred to as the l^{th} **moment measure**.

In terms of the moment measures, the normalization $\rho(\mathcal{F}) = 1$ becomes

$$\mathbf{m}^{(0)}(\mathcal{K}) = 1, \quad (2.25)$$

whereas the relations (2.20) and (2.21) can be written as

$$\mathcal{S}(\rho) = \iint_{\mathcal{K} \times \mathcal{K}} \mathcal{L}[pq] d\mathbf{m}^{(2)}(p) d\mathbf{m}^{(2)}(q) \quad (2.26)$$

$$\mathcal{T}(\rho) = \iint_{\mathcal{K} \times \mathcal{K}} |pq|^2 d\mathbf{m}^{(2)}(p) d\mathbf{m}^{(2)}(q) \quad (2.27)$$

$$\int_{\mathcal{K}} p d\mathbf{m}^{(1)} = \int_{\mathcal{F}} p d\rho = \int_M F(x) d\mu(x). \quad (2.28)$$

Working with the $\mathbf{m}^{(l)}$ has the advantage that they are measures on the *compact* space \mathcal{K} . We also learn that two measures ρ and $\tilde{\rho}$ whose moment measures coincide yield the same values for the functionals \mathcal{S} and \mathcal{T} as well as for the integral (2.28) entering the constraints. Therefore, it is useful to consider two measures as being *equivalent* if their moment measures $\mathbf{m}^{(0)}$, $\mathbf{m}^{(1)}$ and $\mathbf{m}^{(2)}$ coincide. Using this notion, we have a large freedom to modify the measures ρ_k within the equivalence class defined by its moment measures $(\mathbf{m}_k^{(0)}, \mathbf{m}_k^{(1)}, \mathbf{m}_k^{(2)})$. This freedom is indeed a problem for proving convergence of the measures ρ_k , as the following one-dimensional analog shows.

Example 2.11. (*Discontinuous moments*) We consider on \mathbb{R} the family of measures

$$\rho_\tau = \frac{3}{\tau} \delta_0 + \frac{\tau-4}{\tau-1} \delta_1 + \frac{3}{\tau^2-\tau} \delta_\tau, \quad \tau > 1, \quad (2.29)$$

where δ_x denotes the Dirac measure supported at x . These measures all have the same moments

$$\rho_\tau(\mathbb{R}) = 1, \quad \int_{\mathbb{R}} x d\rho_\tau(x) = 1, \quad \int_{\mathbb{R}} x^2 d\rho_\tau(x) = 4, \quad (2.30)$$

and are thus all equivalent in the above sense.

In the limit $\tau \rightarrow \infty$, the measures ρ_τ converge in the $C^0(\mathbb{R})^*$ -topology¹ to the measure $\delta_1(x) dx$, having the moments

$$\delta_1(\mathbb{R}) = 1, \quad \int_{\mathbb{R}} x \delta_1(x) dx = 1, \quad \int_{\mathbb{R}} x^2 \delta_1(x) dx = 1.$$

Hence the total volume is preserved in the limit, and also the first moment is continuous. But the second moment jumps discontinuously as $\tau \rightarrow \infty$. \diamond

This example reveals the undesirable fact that the limit $\rho = \lim_k \rho_k$ in the $C^0(\mathcal{F})^*$ -topology may depend on how the representatives ρ_k of the corresponding moment measures $(\mathbf{m}_k^{(0)}, \mathbf{m}_k^{(1)}, \mathbf{m}_k^{(2)})$ are chosen. In order to bypass this problem, we shall work exclusively with the moment measures. At the very end, we shall then construct a suitable representative ρ of the limiting moment measures. A key step for making this method work is the following a-priori estimate.

Lemma 2.12. *There is a constant $\varepsilon = \varepsilon(f, n) > 0$ such that for every measure ρ on \mathcal{F} the corresponding moment measures (see Definition 2.10) satisfy for all measurable $\Omega \subset \mathcal{K}$ the following inequalities:*

$$\left| \mathbf{m}^{(1)}(\Omega) \right|^2 \leq \mathbf{m}^{(0)}(\Omega) \mathbf{m}^{(2)}(\Omega) \quad (2.31)$$

$$\mathbf{m}^{(2)}(\mathcal{K}) \leq \frac{\sqrt{\mathcal{T}(\rho)}}{\varepsilon}. \quad (2.32)$$

Proof. The inequality (2.31) follows immediately from Hölder's inequality,

$$\left| 2\mathbf{m}^{(1)}(\Omega) \right|^2 \leq \left(\int_{\mathbb{R}\Omega} \|p\| d\rho(p) \right)^2 \leq \rho(\mathbb{R}\Omega) \int_{\mathbb{R}\Omega} \|p\|^2 d\rho(p) \leq 4\mathbf{m}^{(0)}(\Omega) \mathbf{m}^{(2)}(\Omega).$$

To prove (2.32), we introduce the mapping

$$\phi : \mathcal{K} \times \mathcal{K} \rightarrow \mathbb{R} : (p, q) \mapsto |p q|.$$

Clearly, ϕ is continuous and

$$\phi(p, p) = |p^2| = \text{Tr}(p^2) = \|p\|^2 = 1.$$

Thus every point $r \in \mathcal{K}$ has a neighborhood $U(r) \subset \mathcal{K}$ with

$$\phi(p, q) \geq \frac{1}{2} \quad \text{for all } p, q \in U(r). \quad (2.33)$$

Since \mathcal{K} is compact, there is a finite number of points r_1, \dots, r_N such that the corresponding sets $U_i := U(r_i)$ cover \mathcal{K} . Due to the additivity property of measures, there is an index $i \in \{1, \dots, N\}$ such that

$$\mathbf{m}^{(2)}(U_i) \geq \frac{\mathbf{m}^{(2)}(\mathcal{K})}{N}. \quad (2.34)$$

We write \mathcal{T} in the form (2.27) and apply (2.33) as well as (2.34) to obtain

$$\mathcal{T}(\rho) \geq \iint_{U_i \times U_i} |p q|^2 d\mathbf{m}^{(2)}(p) d\mathbf{m}^{(2)}(q) \geq \frac{1}{2} \mathbf{m}^{(2)}(U_i)^2 \geq \frac{\mathbf{m}^{(2)}(\mathcal{K})^2}{2N^2}.$$

Setting $\varepsilon = 1/(\sqrt{2}N)$, the result follows. \square

¹For clarity we point out that by C^0 we always mean the closure of the compactly supported continuous functions with respect to the sup-norm. Thus $C^0(\mathbb{R})$ is the space of continuous functions f with $\lim_{|x| \rightarrow \infty} |f| = 0$.

In view of this lemma and the a-priori bound (2.19), we know that the moment measures are uniformly bounded measures on a compact space \mathcal{K} . Thus, exactly as in Section 1.2, we can apply the Banach-Alaoglu theorem and the Riesz representation theorem to conclude that for a suitable subsequence of the F_k (which for simplicity we denote again by F_k), these measures converge in the $C^0(\mathcal{K})^*$ -topology to positive regular Borel measures,

$$\mathbf{m}_k^{(l)} \rightarrow \mathbf{m}^{(l)} \quad (l \in \{0, 1, 2\}),$$

which again have the properties (2.25), (2.31) and (2.32).

We next consider the Radon-Nikodym decompositions of $\mathbf{m}^{(1)}$ and $\mathbf{m}^{(2)}$ with respect to $\mathbf{m}^{(0)}$ (cf. [10, Section 31]),

$$d\mathbf{m}^{(l)} = f^{(l)} d\mathbf{m}^{(0)} + d\mathbf{m}_{\text{sing}}^{(l)} \quad \text{with } f^{(l)} \in L^1(\mathcal{K}, d\mathbf{m}^{(0)}) \quad (l = 1, 2),$$

where the measures $d\mathbf{m}_{\text{sing}}^{(l)}$ are singular with respect to $d\mathbf{m}^{(0)}$. Evaluating (2.31) for any Ω in the support of $d\mathbf{m}_{\text{sing}}^{(1)}$, the right side vanishes, and thus $\mathbf{m}_{\text{sing}}^{(1)} = 0$. Furthermore, the inequality (2.31) implies that $|f^{(1)}|^2 \leq f^{(2)}$. In particular, we conclude that $f^{(1)}$ even lies in $L^2(\mathcal{K}, d\mathbf{m}^{(0)})$. Setting $f = f^{(1)}$ and $d\mathbf{n}^{(2)} = (f^{(2)} - |f|^2) d\mathbf{m}^{(2)} + d\mathbf{m}_{\text{sing}}^{(2)}$, we obtain the decomposition

$$d\mathbf{m}^{(1)} = f d\mathbf{m}^{(0)}, \quad d\mathbf{m}^{(2)} = |f|^2 d\mathbf{m}^{(0)} + d\mathbf{n}, \quad (2.35)$$

where $f \in L^2(\mathcal{K}, d\mathbf{m}^{(0)})$, and \mathbf{n} is a positive measure which need not be absolutely continuous with respect to $\mathbf{m}^{(0)}$. From the definition (2.23) it is clear that f is odd in the sense that

$$f(-p) = -f(p) \quad \text{for all } p \in \mathcal{K}. \quad (2.36)$$

The remaining task is to represent the limiting moment measures $\mathbf{m}^{(l)}$ in (2.35) by a function $F \in \mathbb{M}$ and a corresponding measure ρ on \mathcal{F} . Unfortunately, there is the basic problem that such a measure ρ can exist only if $\mathbf{m}^{(2)}$ is absolutely continuous with respect to $\mathbf{m}^{(0)}$, as the following consideration shows. Assume conversely that $\mathbf{m}^{(2)}$ is not absolutely continuous with respect to $\mathbf{m}^{(0)}$. Then there is a measurable set $\Omega \subset \mathcal{K}$ with $\mathbf{m}^{(0)}(\Omega) = 0$ and $\mathbf{m}^{(2)}(\Omega) \neq 0$. Assume furthermore that there is a measure ρ on \mathcal{F} which represents the limiting moment measures in the sense that (2.22)–(2.24) hold. From (2.22) we conclude that the set $\mathbb{R}\Omega \subset \mathcal{F}$ has ρ -measure zero. But then the integral (2.24) also vanishes, a contradiction.

This problem can also be understood in terms of the limiting sequence ρ_k . We cannot exclude that there is a star-shaped region $\mathbb{R}\Omega \subset \mathcal{F}$ such that the measures $\rho_k(\mathbb{R}\Omega)$ tend to zero, but the corresponding moment integrals (2.24) have a non-zero limit. Using a notion from the calculus of variations for curvature functionals, we refer to this phenomenon as the possibility of *bubbling*. This bubbling effect is illustrated by the following example.

Example 2.13. (*Bubbling*) We choose $f = 2$, $n = 1$ and again use the Pauli representation (1.16) to identify \mathcal{F} with S^2 . Furthermore, we let $M = [0, 1)$ with μ the Lebesgue measure. For any parameters $\kappa \geq 0$ and $\varepsilon \in (0, \frac{1}{2})$, we introduce the function

$F_\varepsilon : M \rightarrow \mathcal{F}$ by

$$F_\varepsilon(x) = \frac{1}{1-2\varepsilon} \times \begin{cases} -\kappa \varepsilon^{-\frac{1}{2}} \sigma^3 & \text{if } x \leq \varepsilon \\ \mathbf{1} + \sigma^1 \cos(kx) + \sigma^2 \sin(kx) & \text{if } \varepsilon < x \leq 1 - \varepsilon \\ \kappa \varepsilon^{-\frac{1}{2}} \sigma^3 & \text{if } x > 1 - \varepsilon. \end{cases}$$

The corresponding measure ρ_ε on \mathcal{F} has the following properties. On the set

$$S := \{\mathbf{1} + v^1 \sigma^1 + v^2 \sigma^2 \text{ with } (v^1)^2 + (v^2)^2 = 1\},$$

which can be identified with a circle S^1 , ρ_ε is a multiple of the Lebesgue measure. Moreover, ρ_ε is supported at the two points

$$p_\pm := \pm \frac{\kappa \varepsilon^{-\frac{1}{2}}}{1-2\varepsilon} \sigma^3 \quad \text{with} \quad \rho(\{p_+\}) = \rho(\{p_-\}) = \varepsilon. \quad (2.37)$$

A short calculation shows that the identity constraint (C2) is satisfied. Furthermore, the separations of the points p_+ and p_- from each other and from S are either spacelike or just in the boundary case between spacelike and timelike. Thus for computing the action, we only need to take into account pairs (x, y) of points on S . A straightforward computation yields

$$\mathcal{S}(\rho_\varepsilon) = \frac{3}{(1-2\varepsilon)^2}, \quad \mathcal{T}(\rho_\varepsilon) = \frac{6}{(1-2\varepsilon)^2} + \frac{16\kappa^2}{(1-2\varepsilon)^3} + \frac{16\kappa^4}{(1-2\varepsilon)^4}. \quad (2.38)$$

Let us consider the limit $\varepsilon \searrow 0$. From (2.38) we see that the functionals \mathcal{S} and \mathcal{T} converge,

$$\lim_{\varepsilon \searrow 0} \mathcal{S} = 3, \quad \lim_{\varepsilon \searrow 0} \mathcal{T} = 6 + 16(\kappa^2 + \kappa^4). \quad (2.39)$$

Moreover, there are clearly no convergence problems on the set S . Thus it remains to consider the situation at the two points p_\pm , (2.37), which move to infinity as ε tends to zero. These two points enter the moment measures only at the corresponding normalized points $\hat{p}_\pm = p_\pm / \|p_\pm\| \in \mathcal{K}$. A short calculation shows that the limiting moment measures $\mathbf{m}^{(l)} = \lim_{\varepsilon \searrow 0} \mathbf{m}_\varepsilon^{(l)}$ satisfy the relations

$$\mathbf{m}^{(0)}(\{\hat{p}_\pm\}) = \mathbf{m}^{(1)}(\{\hat{p}_\pm\}) = 0 \quad \text{but} \quad \mathbf{m}^{(2)}(\{\hat{p}_\pm\}) = \kappa^2 > 0.$$

Hence $\mathbf{m}^{(2)}$ is indeed *not* absolutely continuous with respect to $\mathbf{m}^{(0)}$.

In order to clarify the connection to earlier examples, we point out that, in contrast to Examples 2.6 and 2.7, the “bubbles” have ρ -measure zero, so that the total measure is preserved in the limit. Nevertheless, the bubbles carry non-zero second moments. In Example 2.11 the situation is simpler because the moments (2.30) are independent of τ , whereas in the present example the singularity of the moment measure appears only in the limit $\varepsilon \searrow 0$. In particular, the moment measures (2.30) can be represented by a measure ρ (for example by choosing ρ according to (2.29) with $\tau = 2$), whereas in the present example the corresponding representation (2.22)–(2.24) cannot be given.

To avoid misunderstandings, we also point out that this example does *not* show that bubbling really occurs for minimizing sequences, because we do not know whether the family $(F_\varepsilon)_{0 < \varepsilon < 1/2}$ is minimizing. But at least, our example shows that bubbling makes it possible to arrange arbitrary large values of \mathcal{T} , without increasing the action \mathcal{S} (see (2.39) for large κ). In particular, for large prescribed \mathcal{T} , the action here is strictly smaller than in Example 2.8 (cf. (2.15) and (2.16)). \diamond

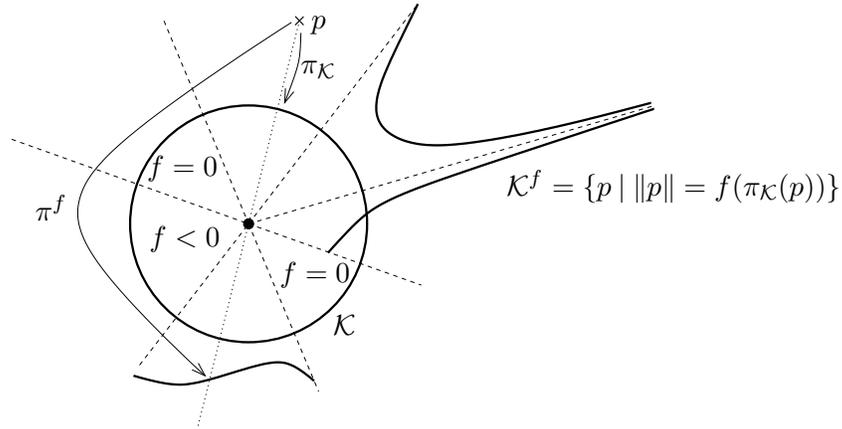


FIGURE 3. Example for the sets \mathcal{K} , \mathcal{K}^f and the projections $\pi_{\mathcal{K}}$, π^f .

In order to handle possible bubbling phenomena, it is important to observe that the second moment measure does not enter the constraints (C1) or (C2) (see (2.21) and (2.28)). Therefore, by taking out the term $d\mathbf{n}$ in (2.35) we *decrease* the functionals \mathcal{S} and \mathcal{T} (see (2.26) and (2.27)), without affecting the constraints (C1) or (C2). The following lemma allows us to remove the term $d\mathbf{n}$ in (2.35).

Lemma 2.14. *For every function $F \in \mathbb{M}$ having the moment measures (2.35) there is a function $\tilde{F} \in \mathbb{M}$ whose moment measures $\tilde{\mathbf{m}}^{(l)}$ are given by*

$$\tilde{\mathbf{m}}^{(0)} = \mathbf{m}^{(0)}, \quad d\tilde{\mathbf{m}}^{(1)} = f d\mathbf{m}^{(0)}, \quad d\tilde{\mathbf{m}}^{(2)} = |f|^2 d\mathbf{m}^{(0)}. \quad (2.40)$$

Proof. We first introduce the projection

$$\pi_{\mathcal{K}} : \mathcal{F} \rightarrow \mathcal{K} : p \mapsto \begin{cases} 0 & \text{if } p = 0 \\ \frac{p}{\|p\|} & \text{if } p \neq 0. \end{cases}$$

For the function f in (2.35) we introduce the set $\mathcal{K}^f \subset \mathcal{F}$ and the corresponding projection π^f by

$$\begin{aligned} \mathcal{K}^f &= \{f(p)p \text{ with } p \in \mathcal{K}\} \subset \mathcal{F} \\ \pi^f : \mathcal{F} &\rightarrow \mathcal{K}^f : p \mapsto f(\pi_{\mathcal{K}}(p)) \pi_{\mathcal{K}}(p). \end{aligned}$$

These definitions are illustrated in Figure 3. Finally, we introduce the function \tilde{F} by

$$\tilde{F} : M \rightarrow \mathcal{K}^f \subset \mathcal{F} : x \mapsto \pi^f(F(x)). \quad (2.41)$$

We decompose any measurable set $\Omega \subset \mathcal{K}$ as $\Omega = \Omega_0 \dot{\cup} \Omega_+ \dot{\cup} \Omega_-$, where

$$\Omega_0 = \{p \in \Omega \mid f(p) = 0\}, \quad \Omega_+ = \{p \in \Omega \mid f(p) > 0\}, \quad \Omega_- = \{p \in \Omega \mid f(p) < 0\}.$$

Since f is odd (2.36), we know that $f(0) = 0$ and thus $0 \in \Omega_0$. Using the definition of \tilde{F} , (2.41), it follows that

$$\tilde{\rho}(\Omega_0) = \rho(\{0\}), \quad \tilde{\rho}(\mathbb{R}^+ \Omega_+) = \rho(\Omega_+), \quad \tilde{\rho}(\mathbb{R}^+ \Omega_-) = 0.$$

Moreover, using (2.22) together with the fact that the measure $\tilde{\rho}$ is supported on \mathcal{K}^f , we find

$$\int_{\mathbb{R}_+\Omega_+} \|p\|^l d\tilde{\rho}(p) = 2 \int_{\Omega_+} |f(p)|^l d\mathbf{m}^{(0)}(p) \quad (l \in \{0, 1, 2\}).$$

Similarly,

$$\int_{\mathbb{R}_-\Omega_-} \|p\|^l d\tilde{\rho}(p) = 2 \int_{\Omega_-} |f(p)|^l d\mathbf{m}^{(0)}(p).$$

Using these relations, we can compute the moment measures corresponding to $\tilde{\rho}$ by

$$\begin{aligned} \tilde{\mathbf{m}}^{(0)}(\Omega) &= \frac{1}{2} \tilde{\rho}(\mathbb{R}\Omega_+) + \frac{1}{2} \tilde{\rho}(\mathbb{R}\Omega_-) + \tilde{\rho}(\Omega_0) \\ &= \mathbf{m}^{(0)}(\Omega_+) + \mathbf{m}^{(0)}(\Omega_-) + \mathbf{m}^{(0)}(\Omega_0) = \mathbf{m}^{(0)}(\Omega) \\ \tilde{\mathbf{m}}^{(1)}(\Omega) &= \frac{1}{2} \int_{\mathbb{R}_+\Omega_+} \|p\| d\tilde{\rho}(p) - \frac{1}{2} \int_{\mathbb{R}_-\Omega_-} \|p\| d\tilde{\rho}(p) \\ &= \int_{\Omega_+} f(p) d\mathbf{m}^{(0)}(p) + \int_{\Omega_-} f(p) d\mathbf{m}^{(0)}(p) = \int_{\Omega_+ \cup \Omega_-} f(p) d\mathbf{m}^{(0)}(p) \\ \tilde{\mathbf{m}}^{(2)}(\Omega) &= \frac{1}{2} \int_{\Omega_+ \cup \Omega_-} \|p\|^2 d\tilde{\rho}(p) = \int_{\Omega_+ \cup \Omega_-} |f(p)|^2 d\mathbf{m}^{(0)}(p). \end{aligned}$$

This completes the proof. \square

Applying this lemma to our minimizing sequence, we shall obtain a new minimizing sequence \tilde{F}_k . The next lemma shows that the limiting moment measures of this new sequence can indeed be represented by a function $F \in \mathbb{M}$.

Lemma 2.15. *Let $F_k \in \mathbb{M}$ be a sequence of functions such that the corresponding moment measures $\mathbf{m}_k^{(l)}$, $l \in \{0, 1, 2\}$, converge in the $\mathbb{C}^0(\mathcal{K})^*$ -topology to moment measures $\mathbf{m}^{(l)}$ having the Radon-Nikodym representation*

$$d\mathbf{m}^{(1)} = f d\mathbf{m}^{(0)}, \quad d\mathbf{m}^{(2)} = |f|^2 d\mathbf{m}^{(0)} \quad (2.42)$$

with $f \in L^2(\mathcal{K}, d\mathbf{m}^{(0)})$. Then there is a function $F \in L^2(M, \mathcal{F}, d\mu)$ such that the corresponding moment measures (as defined by (2.22)–(2.24) and (1.6)) coincide with the moment measures in (2.42).

Proof. If the moment measures corresponding to a function $F \in \mathbb{M}$ coincide with (2.42), it follows from Definition 2.10 that

$$\int_M \|F\|^2 d\mu = \int_{\mathcal{F}} \|p\|^2 d\rho(p) = \mathbf{m}^{(2)}(\mathcal{K}) = \|f\|_{L^2(\mathcal{K}, d\mathbf{m}^{(0)})}^2 < \infty,$$

proving that the function is square integrable, $F \in L^2(M, \mathcal{F}, d\mu)$.

Using the same notation as in the proof of Lemma 2.14, we define the measure ρ on \mathcal{F} by

$$\rho(\{0\}) = \mathbf{m}^{(0)}(\{0\}) \quad \text{and} \quad \rho(U) = 2\mathbf{m}^{(0)}\left(\pi_{\mathcal{K}}(U \cap \mathcal{K}^f)\right) \text{ if } 0 \notin U.$$

Similar as in the proof of Lemma 2.14 one verifies that the moment measures corresponding to ρ indeed coincide with the moment measures in (2.42). Thus it remains to represent ρ by a function $F \in \mathbb{M}$.

As in the proof of Lemma 1.4, we decompose the measure space (M, μ) into an atomic part (M^d, μ^d) and a non-atomic part (M^c, μ^c) (see (1.10)). By modifying the

mappings F_k on sets of measure zero we can again arrange that for every atom $A \in \mathfrak{A}$, the set $F_k(A)$ consist of only one point. The estimate

$$\|F_k(A)\|^2 \mu^c(A) \leq \int_M \|F_k(x)\|^2 d\mu = \mathfrak{m}_k^{(2)}(\mathcal{K}) \xrightarrow{k \rightarrow \infty} \mathfrak{m}^{(2)}(\mathcal{K}) \quad (2.43)$$

shows that for any $A \in \mathfrak{A}$, the sequence $F_k(A)$ is bounded in \mathcal{F} . Thus, just as in the proof of Lemma 1.4, there is a subsequence of the F_k such that the sequence $F_k(A)$ converges for every $A \in \mathfrak{A}$. Again subtracting the resulting limit measure according to (1.12), we obtain a positive ρ^c . Thus it remains to construct a function $g : M^c \rightarrow \mathcal{F}$ which satisfies (1.13).

The method of Lemma 1.4 does not immediately apply because the support of ρ does not need to be bounded. But we can use the following standard exhaustion argument. We introduce the sets \mathcal{F}_L , $L \in \mathbb{N}_0$ by

$$\mathcal{F}_L = \{p \in \mathcal{F} \text{ with } L \leq \|p\| < L + 1\}.$$

Clearly, the \mathcal{F}_L form a partition of \mathcal{F} . Using (1.11), we can iteratively construct a partition M_L of M^c such that $\mu^c(M_L) = \rho(\mathcal{F}_L)$. Exactly as in the proof of Lemma 1.4 we can construct a functions $g_L : M_L \rightarrow \mathcal{F}_L$ with the property

$$\rho^c(\Omega) = \mu^c(g_L^{-1}(\Omega)) \quad \text{for every Borel set } \Omega \subset \mathcal{F}_L.$$

Then the function g defined by $g|_{M_L} = g_L$ has the required property (1.13). \square

2.4. Existence Proofs. We can now complete the proofs of the existence theorems stated in Section 2.1. Theorem 2.1 can be proved with the same methods as Theorem 1.2.

Proof of Theorem 2.1. The set $\mathcal{F}_{(C3)}$ of all matrices satisfying the constraint (C3) is a compact manifold. For a given minimizing sequence $(F_k)_{k \in \mathbb{N}}$ the corresponding measures ρ_k defined by (1.6) are supported on $\mathcal{F}_{(C3)}$. Exactly as in the proof of Lemma 1.3, a subsequence of the ρ_k converges in the $C^0(\mathcal{F}_{(C3)})^*$ -topology to a positive normalized Borel measure on $\mathcal{F}_{(C3)}$. Since the integrands in (2.20) and (2.21) are continuous in p and q , the action converges and the constraints (C1) or (C2) (if considered) are preserved in the limit. As in the proof of Lemma 1.4 we finally represent ρ by a function $F \in \mathbb{M}$. \square

For the remaining proofs we need to use the methods of Section 2.3.

Proof of Theorems 2.2 and 2.3. Let $(F_k)_{k \in \mathbb{N}}$ be a minimizing sequence. According to Lemma 2.14, to any F_k we can associate a function $\tilde{F}_k \in \mathbb{M}$. Using (2.40) and (2.35) in (2.26)–(2.28), we see that

$$\mathcal{S}[\tilde{F}_k] \leq \mathcal{S}[F_k], \quad \mathcal{T}[\tilde{F}_k] \leq \mathcal{T}[F_k] \quad \text{and} \quad \int_M \tilde{F}_k(x) d\mu(x) = \int_M F_k(x) d\mu(x).$$

Hence replacing the F_k by the \tilde{F}_k , we obtain a new minimizing sequence which still satisfies all the constraints. As in the proof of Lemma 1.3, the Banach-Alaoglu theorem and the Riesz representation theorem yield that for a subsequence of the F_k (denoted again by F_k), the corresponding moment measures converge in the $C^0(\mathcal{K})^*$ -topology to bounded regular Borel measures $\mathfrak{m}^{(l)}$, $l \in \{0, 1, 2\}$. The property (2.40) of the F_k yields that the measures $\mathfrak{m}^{(1)}$ and $\mathfrak{m}^{(2)}$ have the Radon-Nikodym representation (2.42)

with $f \in L^2(\mathcal{K}, d\mathbf{m}^{(0)})$. According to Lemma 2.15, we can represent the moment measures by a function $F \in L^2(M, \mathcal{F}, d\mu)$, being the desired minimizer. \square

2.5. Remarks and Open Problems. We conclude this chapter by a few remarks and a brief discussion of open problems. We first note that Theorems 2.2 and 2.3 remain valid if other constraints are imposed. For example, one could prescribe only some of the $2n$ non-trivial eigenvalues of $F(x)$, or one could prescribe the trace of $F(x)$. Such generalizations are straightforward and shall not be considered here. More interesting are the following open problems:

- (A) It is not clear whether Theorem 2.3 remains valid if the constraint $\mathcal{T}[F] \leq C$ is replaced by $\mathcal{T}[F] = C$. In other words, does the bubbling phenomenon discussed in Section 2.3 really occur for minimal sequences, or does it only reflect a shortcoming of our method of proof? We again point out that Example 2.13 does not prove bubbling, because it is unknown whether the constructed family F_ε is minimal.
- (B) It is an open problem whether Theorem 2.3 holds without the constraint $\mathcal{T}[F] \leq C$ if one assumes that M is a finite set and μ the counting measure. We point out that the counter Example 2.9 works only for a continuous measure, but the situation for discrete measures is unclear. A partial result in this direction was obtained in [6, Theorem 2.9], where an analog of Theorem 2.3 was proved without the constraint $\mathcal{T}[F] \leq C$ for M a finite set and μ the counting measure, assuming in addition the trace constraint (C1) (see also Theorem 3.3 below and the corresponding statement for the local correlation matrices in Section 3.2). But it is an open (and seemingly difficult) problem to prove the same for the identity constraint (C2).
- (C) Treating the constraint in the variational principle of Theorem 2.3 with the Lagrange multiplier method, one finds that every minimizer F is a critical point of the functional $\mathcal{S} - \kappa\mathcal{T}$ for a suitable Lagrange multiplier $\kappa \in \mathbb{R}$. It is not clear what the value of the Lagrange multiplier is, nor how it depends on the parameter C . What is the range of the Lagrange multipliers if C varies over \mathbb{R}^+ ? Of particular interest are the negative values of κ , because this case cannot be handled using Theorem 2.2.
- (D) Almost nothing is known about uniqueness. Clearly, we have the freedom to perform isomorphisms of the measure space M as well as unitary transformations of \mathbb{C}^f . Moreover, we are free to change the function F as long as the moment measures remain unchanged. But are the minimizers unique up to these obvious transformations, at least if μ is a non-atomic measure?
- (E) In the setting of Section 1.5, we saw examples of non-trivial minimizers. Do distributional minimizers as in Example 1.11 also exist if $\beta > 0$? Are the minimizers in the setting of Lemma 1.12 or Lemma 1.13 smooth?
- (F) It would be interesting to know more about the regularity of the minimizers in the general setting of Chapter 2. Is every minimizing measure ρ supported on a set $\mathcal{K}^f \subset \mathcal{F}$? Under which conditions is the set \mathcal{K}^f a submanifold of \mathcal{K} ? If yes, in which situations is ρ absolutely continuous with respect to the Lebesgue measure on \mathcal{K} ? When is the corresponding Radon-Nikodym derivative a continuous or even smooth function on \mathcal{K}^f ?

Answering these questions goes beyond the scope of this paper. We now proceed to the applications.

3. VARIATIONAL PRINCIPLES IN INDEFINITE INNER PRODUCT SPACES

Let us briefly outline the physical context in which causal variational principles arise (for details see [3] or the review articles [4, 7]). The Dirac wave functions in Minkowski space $(M, \langle \cdot, \cdot \rangle)$ (or more generally on a Lorentzian manifold) have four complex components, and they are endowed with an indefinite inner product $\langle \psi | \phi \rangle$ of signature $(2, 2)$ (this inner product is usually written as $\langle \psi | \phi \rangle = \overline{\psi} \phi$ with $\overline{\psi} = \psi^\dagger \gamma^0$ the so-called adjoint spinor and $\gamma^0 = \text{diag}(1, 1, -1, -1)$). Integrating this inner product over space-time defines an inner product on the wave functions,

$$\langle \psi | \phi \rangle = \int_M \langle \psi | \phi \rangle d^4x. \quad (3.1)$$

A system of Dirac particles can be described by an operator P which is built up of an ensemble of wave functions,

$$P\phi = - \sum_a \langle \psi_a | \phi \rangle \psi_a, \quad (3.2)$$

where the index a runs over all the quantum numbers of the occupied states of the system. The operator P is referred to as the fermionic projector or, more generally, the *fermionic operator*. In [3] it was proposed to formulate the physical equations in terms of a variational principle for the fermionic operator in space-time. It is a main advantage of this approach that the metric, causal and even topological structure of space-time does not enter the variational principle. This makes it possible to formulate the physical equations on a set of points, referred to as *discrete space-time*. As a consequence of a spontaneous symmetry breaking effect [5], the fermionic operator induces additional structures on the space-time points, and there is some evidence that for systems involving many particles and space-time points, these structures give rise to the usual topological and causal structure of the space-time continuum [7]. Moreover, our variational principle can be analyzed in Minkowski space in the so-called *continuum limit*. In view of these developments, it is of interest to analyze the variational principle both in the discrete and continuous settings. In order to treat these two cases in a unified setting, M is best described by a general measure space.

Analyzing variational principles in the general setting (3.1) and (3.2) leads to two convergence problems: First, the space-time integral (3.1) need not be finite, and secondly the sum in (3.2) might diverge. In order to avoid these problems, we shall assume that M has *finite volume*. Furthermore, we make the sum in (3.2) finite by considering only a *finite number of particles*. In this chapter we shall give a general existence proof in finite volume and for a finite number of particles. In Chapter 4, we will prove existence for homogeneous systems even in infinite volume for an infinite number of particles, assuming merely a momentum cutoff.

Before introducing the general setup and stating our results, we mention one particular difficulty in analyzing variational principles in indefinite inner product spaces. The inner product (3.1) and also the action of any physically reasonable variational principle are invariant under transformations of the wave functions of the form

$$\psi(x) \rightarrow U(x) \psi(x) \quad \text{with } U(x) \in \text{U}(2, 2), \quad (3.3)$$

referred to as *local gauge transformations*. Since the group $\text{U}(2, 2)$ is non-compact, there is a large freedom to change the wave functions without affecting the physical action.

3.1. Definitions and Statement of Results. Let (M, μ) be a measure space of total volume $\mu(M) = 1$ and $(V, \langle \cdot | \cdot \rangle)$ a $2n$ -dimensional complex vector space, endowed with a non-degenerate sesquilinear form of signature (n, n) (for basic definitions see [9]). We consider the vector space $H = L^2(M, V, d\mu)$ of square-integrable functions from M to V and introduce on M the sesquilinear form

$$\langle \psi | \phi \rangle = \int_M \langle \psi(x) | \phi(x) \rangle d\mu(x). \quad (3.4)$$

Thus $(H, \langle \cdot | \cdot \rangle)$ is an indefinite inner product space. A function $\psi \in H$ has $2n$ components and is called a *wave function*. The parameter n is referred to as the *spin dimension*. We introduce the *fermionic operator* $P : H \rightarrow H$ as an operator having the following properties (A) and (B1) or (B2):

(A) P is *symmetric* in the sense that

$$\langle P\psi | \phi \rangle = \langle \psi | P\phi \rangle \quad \text{for all } \phi, \psi \in H.$$

(B1) The operator P has *finite rank*, $\dim P(H) \leq f < \infty$. It satisfies the *trace constraint*

$$\text{tr}(P) = f$$

(where “tr” denotes the trace of operators in H). Furthermore, the operator $(-P)$ is *positive* in the sense that

$$\langle \psi | (-P)\psi \rangle \geq 0 \quad \text{for all } \psi \in \mathcal{H}.$$

(B2) The operator P is a *projector* on a *negative definite* subspace of H of *dimension* $f < \infty$.

In case (B2), the operator P is called *fermionic projector*. In this case, the calculations

$$\text{tr}(P) = \text{rank}(P) = f, \quad \langle \psi | (-P)\psi \rangle = -\langle \psi | P^2\psi \rangle = -\langle P\psi | P\psi \rangle \geq 0$$

show that condition (B1) is again satisfied. Thus (B2) is a special case of (B1). We refer to the rank of P as the *number of particles*. Note that for a fermionic projector, the number of particles is equal to the parameter f , whereas in case (B1) the number of particles is only bounded from above by f . For brevity, we refer to the system $(P, H, \langle \cdot | \cdot \rangle)$ as a *fermion system*, and M are the *space-time points*.

Since P has finite rank and $\langle \cdot | \cdot \rangle$ is non-degenerate, we can clearly represent P by a finite matrix,

$$P\psi = \sum_{k,l=1}^f \psi_k \langle \phi_l | \psi \rangle \quad \text{with } \psi_k, \phi_l \in H.$$

Writing the inner product with an integral (3.4), one sees that P has an integral representation,

$$(P\psi)(x) = \int_M P(x, y) \psi(y) d\mu(y) \quad \text{with} \quad P(x, y) \in L^2(M \times M, L(V)) \quad (3.5)$$

(where $L(V)$ denotes the space of linear mappings from V to itself). We refer to $P(x, y)$ as the *kernel* of the fermionic operator. Next, we introduce the *closed chain* A_{xy} by

$$A_{xy} = P(x, y) P(y, x). \quad (3.6)$$

Note that, for any fixed x and y , the closed chain is a symmetric linear mapping of V to itself. More generally, for any endomorphism A of V we define

$$\text{the spectral weight} \quad |A| = \sum_{l=1}^{2n} |\lambda_l|, \quad (3.7)$$

where λ_l are the eigenvalues of A , counted with algebraic multiplicities. We introduce

$$\boxed{\text{the Lagrangian} \quad \mathcal{L}[A_{xy}] = |A_{xy}^2| - \frac{1}{2n} |A_{xy}|^2} \quad (3.8)$$

and define the functionals \mathcal{S} and \mathcal{T} by

$$\mathcal{S}[P] = \iint_{M \times M} \mathcal{L}[A_{xy}] d\mu(x) d\mu(y) \quad (3.9)$$

$$\mathcal{T}[P] = \iint_{M \times M} |A_{xy}|^2 d\mu(x) d\mu(y). \quad (3.10)$$

These definitions are similar to (2.3)–(2.5). However, we point out that now the mathematical setting is very different; in particular the functionals now depend on the fermionic operator P . Again using Definition 2.4, the eigenvalues λ_j^{xy} of the closed chain A_{xy} induce on M a *causal structure*. Now we even get a connection to the usual notion of causality: If the fermionic operator describes vacuum Dirac seas, the causal structure of Definition 2.4 coincides precisely with the causal structure of Minkowski space (for details see [7, Section 6]).

We prove the following existence results.

Theorem 3.1. *For given parameters $f, n \in \mathbb{N}$ with $f \geq 2n$ and a parameter ν in the range (2.8), we consider the variational principle*

$$\text{minimize } \mathcal{T}[P] + \nu \mathcal{S}[P]$$

within the class of all fermionic operators with the properties (A) and either (B1) or (B2). Then the minimum is attained.

Theorem 3.2. *For given parameters $f, n \in \mathbb{N}$ with $f \geq 2n$ and a constant $C > 0$, we consider the variational principle*

$$\text{minimize } \mathcal{S}[P] \text{ on } \mathcal{P}_C := \{P \text{ with } \mathcal{T}[P] \leq C\}$$

within the class of all fermionic operators with the properties (A) and either (B1) or (B2). Then the minimum is attained.

The method of proof is to consider the corresponding local correlation matrices (see Section 2.3), making it possible to apply the results of Chapter 2. In this reformulation, the conditions (B1) and (B2) will correspond precisely to the conditions (C1) and (C2) on page 18, respectively.

Before entering these constructions, we briefly discuss the above theorems and put them in the context of previous work. In [6] similar existence results were obtained in the special case where M is a finite set and μ the *counting measure*. These assumptions are a major simplification because then the vector space H is finite-dimensional. The remaining difficulty is to handle the non-compact gauge freedom (3.3), and this problem is overcome by suitable a-priori estimates and a gauge fixing procedure. In order to avoid confusion of notation, we point out that in [6] the Lagrangian (3.8) is referred to as the critical Lagrangian. Also, instead of minimizing the functional

$\mathcal{T}[P] + \nu \mathcal{S}[P]$, in [6] the action corresponding to the Lagrangian $\mathcal{L}_\mu = |A^2| - \mu|A|^2$ is considered for $\mu > \frac{1}{2n}$. These different functionals can easily be transformed into each other, and one sees that the procedure in [6] is equivalent to minimizing $\mathcal{T}[P] + \nu \mathcal{S}[P]$ for any $\nu > 0$. The procedure in the present paper has the advantage that we can also consider negative values of ν .

There are a few general differences between the results in [6] and the above theorems. First, in [6] the analog of Theorem 3.2 is proved under the constraint $\mathcal{T}[P] = C$ (instead of $\leq C$). This can be understood from the fact that for a finite counting measure, the bubbling phenomenon of Section 2.3 cannot appear (as is obvious from the inequality (2.43) for atoms of our measure). Furthermore, it is worth noting that the following result for a finite counting measure (see [6, Theorems 2.5 and 2.9]) does *not* carry over to continuous measures.

Theorem 3.3. *Suppose that μ is a finite counting measure. Then the variational principle*

$$\text{minimize } \mathcal{S}[P]$$

attains its minimum if considered in one of the following two situations:

- (1) *The fermionic operator satisfies (A) and (B1).*
- (2) *The fermionic operator satisfies (A) and (B2), and P is homogeneous in the sense that $\text{Tr}(P(x, x)) = \text{Tr}(P(y, y))$ for all $x, y \in M$.*

The three-dimensional Dirac sphere (Example 2.9) shows that this theorem does not hold for continuous measures, because there are divergent minimal sequences. Thus there are situations where minimizers exist only due to the discreteness of space-time.

We finally point out that in [2] examples of minimizers are constructed for a small number of particles and space-time points, and the resulting causal structure is discussed.

3.2. Reformulation in Terms of Local Correlation Matrices. A direct approach to proving Theorems 3.1 and 3.2 seems difficult because the inner product space $(H, \langle \cdot | \cdot \rangle)$ is infinite-dimensional. In such infinite-dimensional indefinite inner product spaces (also called Krein spaces, see for example [1]), the functional analytic methods are quite limited, making it hard to control the behavior of minimizing sequences (P_k) of our variational principles. A particular problem in this setting is the above-mentioned gauge freedom (3.3). In order to bypass these difficulties, we shall proceed differently, making essential use of the fact that the operator P has finite rank. More precisely, our method is to choose convenient generators ψ_1, \dots, ψ_f of the image of P and to consider the so-called *local correlation matrices* F_x defined by

$$(F_x)_k^j = - \prec \psi_j(x) | \psi_k(x) \succ . \quad (3.11)$$

We shall see that the functionals \mathcal{S} and \mathcal{T} as well as the constraints (B1) and (B2) can be reformulated purely in terms of the local correlation matrices. This remarkable fact will make it possible to apply the results of Chapter 2, giving us minimizing local correlation matrices. In Section 3.3 we will conclude the proof by constructing a corresponding fermionic operator.

We first specify which generators ψ_1, \dots, ψ_f of $P(H)$ we want to use in (3.11).

Lemma 3.4. *There are vectors $\psi_1, \dots, \psi_f \in H$ such that*

$$P\psi = - \sum_{l=1}^f \psi_l \langle \psi_l | \psi \rangle \quad \text{for all } \psi \in H. \quad (3.12)$$

Proof. It is convenient to work in V with a fixed pseudo-orthonormal basis (e_i) where the inner product has the standard representation with a signature matrix S ,

$$\langle u | v \rangle = \langle u, Sv \rangle_{\mathbb{C}^{2f}} \quad \text{where} \quad S = \text{diag}(\underbrace{1, \dots, 1}_{n \text{ times}}, \underbrace{-1, \dots, -1}_{n \text{ times}}). \quad (3.13)$$

The signature matrix can be regarded as an operator on V . Alternatively, we can consider S as an operator on H , acting by pointwise multiplication (i.e. $(S\psi)(x) := S(\psi(x))$). This makes it possible to represent the inner product on H in terms of the standard L^2 scalar product by

$$\langle \psi | \phi \rangle = \langle \psi, S\phi \rangle_{L^2(M, V, d\mu)}. \quad (3.14)$$

Obviously, $S^2 = \mathbb{1}$ and S is symmetric with respect to both $\langle \cdot | \cdot \rangle$ and $\langle \cdot | \cdot \rangle_{L^2}$.

As the operator $(-P)$ is symmetric and positive on $(H, \langle \cdot | \cdot \rangle)$, the operator $(-SP)$ is symmetric and positive semi-definite on the Hilbert space $(H, \langle \cdot | \cdot \rangle_{L^2})$. Using furthermore that the operator $(-SP)$ has rank at most f , we can diagonalize this operator and choose orthonormal eigenvectors ϕ_1, \dots, ϕ_f which span its image. Since $(-PH)$ is positive semi-definite, the corresponding eigenvalues $\kappa_1, \dots, \kappa_f$ are non-negative. Thus the operator $(-PH)$ has the representation

$$(-SP)(\psi) = \sum_{l=1}^f \kappa_l \phi_l \langle \phi_l | \psi \rangle_{L^2}.$$

Multiplying by $(-S)$ and using (3.14) together with the fact that $S^2 = \mathbb{1}$ and that S symmetric with respect to $\langle \cdot | \cdot \rangle_{L^2}$, we obtain a similar representation for P ,

$$P\psi = - \sum_{l=1}^f \kappa_l S\phi_l \langle S\phi_l | \psi \rangle.$$

Setting $\psi_l = \sqrt{\kappa_l} S\phi_l$ the result follows. \square

We next rewrite the fermionic operator and the local correlation matrices in a compact form. Comparing (3.12) with (3.5) and (3.4), we find that

$$P(x, y)v = - \sum_{l=1}^f \psi_l(x) \langle \psi_l | v \rangle \quad \text{for all } v \in V. \quad (3.15)$$

Introducing the operators

$$\left. \begin{aligned} \pi_x : V &\rightarrow \mathbb{C}^f : v \mapsto (\langle \psi_l(x) | v \rangle)_{l=1, \dots, f} \\ \iota_x : \mathbb{C}^f &\rightarrow V : u \mapsto - \sum_{l=1}^f u_l \psi_l(x), \end{aligned} \right\} \quad (3.16)$$

the identities (3.15) and (3.11) can be written in the simple form

$$\boxed{\begin{aligned} P(x, y) &= \iota_x \pi_y : V \rightarrow V \\ F_x &= \pi_x \iota_x : \mathbb{C}^f \rightarrow \mathbb{C}^f. \end{aligned}} \quad (3.17)$$

The next lemma gives the connection to the setting of Chapter 2.

- Lemma 3.5.** (i) *For every $x \in M$, the local correlation matrix F_x is Hermitian. It has at most n positive and at most n negative eigenvalues.*
- (ii) *In cases (B1) or (B2) (on page 33), the function $F(x) = F_x$ satisfies the conditions (C1) and (C2) (on page 18), respectively.*
- (iii) *Denoting the eigenvalues of the matrix $F_x F_y$ as in (2.1), the $\lambda_1^{xy}, \dots, \lambda_{2n}^{xy}$ coincide precisely with the eigenvalues of the closed chain $P(x, y) P(y, x)$, counted with algebraic multiplicities.*

Proof. It is obvious from the definition (3.11) that F_x is Hermitian. Also, the number of its positive and negative eigenvalues is bounded by the signature n of V . This proves (i).

To prove (ii), we integrate (3.11) over x and use (3.4) to obtain

$$\int_M (F_x)_k^j d\mu(x) = -\langle \psi_j | \psi_k \rangle . \quad (3.18)$$

Taking the trace and using (3.12), we conclude that condition (B1) implies (C1). If (B2) is satisfied, the rank of P equals f , and thus the vectors ψ_1, \dots, ψ_f in (3.12) are linearly independent. Taking the square of (3.12) and using the idempotence of P , we obtain another representation of P ,

$$P\psi = \sum_{k,l} \psi_k \langle \psi_k | \psi_l \rangle \langle \psi_l | \psi \rangle .$$

Comparing these two representations in the basis ψ_1, \dots, ψ_f of $P(H)$, it follows that

$$\langle \psi_j | \psi_k \rangle = -\delta_{jk} .$$

In view of (3.18), we conclude that the identity constraint (C2) holds.

To prove (iii), we first recall that for quadratic matrices A and B , the products AB and BA have the same characteristic polynomials (see for example [6, Section 3]). If the matrices are not quadratic, i.e. $A \in \text{Mat}(\mathbb{C}^p, \mathbb{C}^q)$, $B \in \text{Mat}(\mathbb{C}^q, \mathbb{C}^p)$ with $p > q$, we can extend the matrices by zero rows and columns to obtain quadratic $p \times p$ -matrices. Using the above result for quadratic matrices, it follows that

$$\det(AB - \lambda \mathbb{1}_{\mathbb{C}^p}) = \lambda^{p-q} \det(BA - \lambda \mathbb{1}_{\mathbb{C}^q}) . \quad (3.19)$$

In words, the matrices AB and BA have the same eigenvalues and algebraic multiplicities, up to the zero eigenvalues whose multiplicity is obvious counting dimensions.

We now write the product of the local correlation matrices according to (3.17) as

$$F_x F_y = AB \quad \text{where} \quad A = \iota_x \text{ and } B = \pi_x \iota_y \pi_y .$$

Applying (3.19), we see that this matrix has (up to the obvious zero eigenvalues) the same eigenvalues and multiplicities as the matrix

$$BA = \pi_x \iota_y \pi_y \iota_x = P(x, y) P(y, x) ,$$

where in the last step we used (3.17). This proves (iii). \square

This lemma shows that considering the function $F(x) = F_x$, we are precisely in the setting of Chapter 2. In particular, Theorems 2.2 and 2.3 yield minimizing local correlation matrices.

3.3. Reconstruction of the Fermion System. The next lemma shows that the local correlation matrices can always be represented by a suitable fermionic operator P .

Lemma 3.6. *For any function $F \in L^2(M, \mathcal{F}, d\mu)$ there is a kernel $P \in L^4(M \times M, L(V))$ such that for every $x \in M$, the local correlation matrix (3.17) coincides with $F(x)$. The corresponding fermionic operator P satisfies the condition (A). If the conditions (C1) or (C2) (on page 18) are satisfied, then the fermionic operator satisfies the conditions (B1) or (B2) (on page 33), respectively.*

Proof. For given $x \in M$ we diagonalize the matrix $F(x)$ by a unitary transformation U ,

$$F(x) = UDU^{-1} \quad \text{with } U \in U(\mathbb{C}^f) \text{ and } D = \text{diag}(\nu_1, \dots, \nu_f).$$

We order the eigenvalues such that (2.6) holds and $\nu_{2n+1}, \dots, \nu_f = 0$. Hence introducing the matrices

$$\rho = \text{diag}(\sqrt{|\nu_1|}, \dots, \sqrt{|\nu_f|}) \quad \text{and} \quad s = \text{diag}(\underbrace{1, \dots, 1}_{n \text{ times}}, \underbrace{-1, \dots, -1}_{n \text{ times}}, \underbrace{0, \dots, 0}_{f-2n \text{ times}}), \quad (3.20)$$

we have the decomposition

$$F(x) = -U\rho s\rho U^{-1}.$$

We now introduce the vectors $\psi_1(x), \dots, \psi_k(x) \in V$ by

$$(\psi_l)^a = (\rho U^{-1})_l^a, \quad a = 1, \dots, 2n,$$

where in V we again work in the basis where the inner product has the form (3.13). Carrying out this construction for every $x \in M$, we obtain functions $\psi_l : M \rightarrow V$. Since $F \in L^2$, its eigenvalues ν_j are square integrable, and due to the square roots in (3.20) and the unitarity of the transformation U , the functions ψ_l are in $L^4(M, V, d\mu) \subset H$. Hence (3.12) defines a fermionic operator P with $P(x, y) \in L^4(M \times M, L(V), d\mu)$. Furthermore, from the above construction it follows that

$$(F_x)_l^k = -\langle \psi_k(x), S\psi_l(x) \rangle_{\mathbb{C}^{2n}} = -\langle \psi_k(x), \psi_l(x) \rangle, \quad (3.21)$$

and thus in view of (3.11) we see that the local correlation matrix F_x indeed coincides with the matrix $F(x)$.

Taking the trace of (3.18) and using (3.12) we obtain

$$\text{tr } P = - \int_M \text{Tr}(F(x)) d\mu(x),$$

and thus (C1) indeed implies (B1). If (C2) holds, we obtain from (3.18) that the vectors ψ_1, \dots, ψ_f are mutually orthogonal and normalized to $\langle \psi_l | \psi_l \rangle = -1$. Hence the fermionic operator (3.12) is a projector on a negative definite subspace of H of dimension f . \square

In view of this lemma, Theorem 3.1 and Theorem 3.2 follow immediately from Theorem 2.2 and Theorem 2.3, respectively.

4. A VARIATIONAL PRINCIPLE IN INFINITE SPACE-TIME VOLUME

As explained at the beginning of Chapter 3, the variational principles so far were restricted in that the space-time volume and the number of particles had to be finite. We now introduce a class of variational principles in *infinite space-time volume*, which may involve an *infinite number of particles*. On the other hand, we need to specialize our setting by assuming that our system is *homogeneous* in the sense that the kernel of

the fermionic projector $P(x, y)$ depends only on the difference vector $y - x$. This makes it necessary to assume that space-time has an underlying vector space structure, and thus this setting is of main interest in two situations: in the so-called *continuous case* we assume that $(M, \langle \cdot, \cdot \rangle)$ is Minkowski space and μ is the Lebesgue measure on M , whereas in the so-called *discrete case* we assume that $(M, \langle \cdot, \cdot \rangle)$ is a periodic lattice in Minkowski space (i.e. a discrete subgroup of \mathbb{R}^4) and μ is the counting measure. Generalizations of these two cases are clearly possible, but will not be considered here.

The main simplification in the homogeneous setting is that $P(x, y)$ can be written as a Fourier transform, i.e. in the usual physics notation

$$P(x, y) = \int_{\hat{M}} \frac{d^4 p}{(2\pi)^4} \hat{P}(p) e^{i\langle p, y-x \rangle},$$

where \hat{M} is momentum space, which in the continuum case is isomorphic to Minkowski space, whereas in the discrete case \hat{M} is a primitive cell of the reciprocal lattice. In order to obtain a nice measure-theoretic framework, we here combine the product $\hat{P}(p) d^4 p$ into a Borel measure $d\nu$, taking values in $L(V)$, where $(V, \langle \cdot | \cdot \rangle)$ is again an indefinite inner product space of signature (n, n) . In order to describe a completely filled Dirac sea in the vacuum, the measure $d\nu$ would take the form (see for example [7, Section 6])

$$d\nu(p) = (p_j \gamma^j + m) \delta(\langle p, p \rangle - m^2) \Theta(-p^0) d^4 p, \quad (4.1)$$

where γ^j are the Dirac matrices in Minkowski space, and $V = \mathbb{C}^4$ endowed with the inner product $\langle \psi | \phi \rangle = \bar{\psi} \phi$, where $\bar{\psi} = \psi^\dagger \gamma^0$ is the adjoint spinor. This measure has the remarkable property that $-\nu$ is positive in the sense that

$$\langle v | (-\nu(\Omega)) v \rangle \geq 0 \quad \text{for all } v \in V. \quad (4.2)$$

Unfortunately, measures of the form (4.1) lead to ultraviolet problems. In order to avoid these problems, we shall assume that the measure $d\nu$ is supported in a given bounded subset $\hat{K} \subset \hat{M}$ (this is clearly no restriction in the discrete case, where already \hat{M} is bounded). This motivates the following definition.

Definition 4.1. *Consider a regular Borel measure ν on a bounded set $\hat{K} \subset \hat{M}$ taking values in $L(V)$ with the following properties:*

- (i) *For every $v \in V$, the measure $d \langle v | \nu v \rangle$ is a finite real measure.*
- (ii) *For every Borel set $\Omega \subset \hat{K}$, the operator $-\nu(\Omega) \in L(V)$ is positive (4.2).*

*Then ν is called a **negative definite measure** on \hat{K} with values in $L(V)$.*

For a given negative definite measure ν , we introduce the *kernel* of the fermionic operator by

$$P(\xi) = \int_{\hat{K}} e^{i\langle p, \xi \rangle} d\nu(p), \quad \text{where } \xi \equiv y - x. \quad (4.3)$$

Introducing the corresponding *fermionic operator* P by

$$(P\psi)(y) = \int_M P(y - x) \psi(x) d\mu(x),$$

this operator is well-defined for example on the test functions $C_0^\infty(M, V)$. We point out that this operator will in general have infinite rank, and thus (adopting the notion from Section 3.1) the total number of particles is infinite. However, the quantity

$$f_{\text{loc}} := \text{Tr}(P(0)) \quad (4.4)$$

is finite; it can be interpreted as the local particle density, which for our homogeneous system is constant in space-time.

Following the procedure in Chapter 3, we introduce the closed chain by $A(\xi) = P(\xi)P(-\xi)$ and define the spectral weight and the Lagrangian by (3.7) and (3.8), respectively. However, the space-time integrals in (3.9) and (3.10) do not converge, because rewriting them as

$$\iint_{M \times M} d\mu(x) d\mu(y) \cdots = \int_M d\mu(x) \int_M d\mu(\xi) \cdots$$

and carrying out the ξ -integral, our homogeneity assumption implies that the resulting function is constant, so that the x -integral necessarily diverges. This divergence is an artifact of working in infinite volume. Keeping in mind that in finite volume (obtained for example by compactifying space-time to a torus) the x -integral would give rise to an irrelevant constant, it is natural to simply drop the outer integral. This leads us to introduce the functionals \mathcal{S} and \mathcal{T} by

$$\mathcal{S}[\nu] = \int_M \mathcal{L}[A(\xi)] d\mu(\xi), \quad \mathcal{T}[\nu] = \int_M |A(\xi)|^2 d\mu(\xi). \quad (4.5)$$

We are now ready to state the main result of this chapter.

Theorem 4.2. *Let $(\nu_k)_{k \in \mathbb{N}}$ be a sequence of negative definite measures on the bounded set $\hat{K} \subset \hat{M}$ satisfying one of the following two conditions:*

- (I) *Assume that (M, μ) is Minkowski space with the Lebesgue measure or a lattice with the counting measure. Assume furthermore that the functional \mathcal{T} is bounded,*

$$\mathcal{T}[\nu_k] \leq C \quad \text{for all } k \in \mathbb{N}.$$

- (II) *Assume that (M, μ) is a lattice with the counting measure. Assume furthermore that the functional \mathcal{S} is bounded,*

$$\mathcal{S}[\nu_k] \leq C \quad \text{for all } k \in \mathbb{N},$$

and that the local particle density is bounded away from zero in the sense that there is a constant $\varepsilon > 0$ with

$$\text{Tr}(P[\nu_k](0)) \geq \varepsilon \quad \text{for all } k \in \mathbb{N}. \quad (4.6)$$

Then there is a subsequence (ν_{k_l}) and a series of unitary transformations U_l on V such that the measures $U_l \nu_{k_l} U_l^{-1}$ converge in the $C^0(\hat{K})^$ -topology to a negative definite measure ν with the properties*

$$\mathcal{T}[\nu] \leq \liminf_k \mathcal{T}[\nu_k], \quad \mathcal{S}[\nu] \leq \liminf_k \mathcal{S}[\nu_k].$$

We note that, in contrast to the previous existence theorems, this theorem is stated as a compactness result. By applying it to a minimal sequence, one immediately obtains statements similar to those in Theorems 2.2 and 2.3. The advantage of the above compactness statement is that it applies immediately to situations where additional constraints are imposed (like further conditions on the support, the assumption of a vector-scalar structure, the condition of half-occupied surface states, etc). One only needs to ensure that these constraints are invariant under the unitary transformations U_l , and that they are continuous in the $C^0(\hat{K})^*$ -topology. As a simple example, one may prescribe the local particle density (4.4).

Before coming to the proof, we illustrate the statement of the above theorem by a counter example, which shows why the support of the measures ν_k must be uniformly bounded and why in case (I) one may not replace the functional \mathcal{T} by the action \mathcal{S} .

Example 4.3. (*The Dirac cylinder*) We let $(M, \langle \cdot | \cdot \rangle)$ be Minkowski space with μ the Lebesgue measure. We choose $n = 2$ and $(V, \prec, | \cdot \rangle, \succ)$ as in the example (4.1). For given parameters $\tau, L > 0$, we consider in momentum space $p = (\omega, \vec{p})$ the measure

$$d\nu(p) = \frac{1}{16\pi} \frac{\Theta(L - |\omega|)}{L} \delta(|\vec{p}|^2 - 1) \left[-\sqrt{\tau^2 + 1} \gamma^0 + \tau \vec{p} \vec{\gamma} + \mathbf{1} \right] d^4p.$$

This measure is supported on the cylinder $[-L, L] \times S^2$. Writing the square bracket as $(l^j \gamma_j + \mathbf{1})$, the vector field l has Lorentz length one. Increasing τ describes a Lorentz boost of this vector field.

As is easily verified, ν is a negative definite measure. Computing its Fourier transform, we obtain

$$\begin{aligned} P(\xi) &= \int_{\hat{M}} e^{i\langle p, \xi \rangle} d\nu(p) \\ &= \frac{1}{8\pi} \frac{\sin Lt}{Lt} \left(-\sqrt{\tau^2 + 1} \gamma^0 + i\tau \vec{\gamma} \vec{\nabla} + \mathbf{1} \right) \int_{\mathbb{R}^3} \delta(|\vec{p}|^2 - 1) e^{-i\vec{p} \vec{\xi}} d\vec{p} \\ &= \frac{1}{4} \frac{\sin Lt}{Lt} \left(-\sqrt{\tau^2 + 1} \gamma^0 + i\tau \vec{\gamma} \vec{\nabla} + \mathbf{1} \right) \frac{\sin |\vec{\xi}|}{|\vec{\xi}|} \\ &= \frac{1}{4} \frac{\sin Lt}{Lt} \left\{ \left(-\sqrt{\tau^2 + 1} \gamma^0 + \mathbf{1} \right) \frac{\sin r}{r} + \frac{i\tau \vec{\xi} \vec{\gamma}}{r^2} \left(\cos r - \frac{\sin r}{r} \right) \right\}, \end{aligned}$$

where in the last line we set $r = |\vec{\xi}|$. In particular,

$$\text{Tr}(P(0)) = \frac{1}{4} \text{Tr} \left(-\sqrt{\tau^2 + 1} \gamma^0 + \mathbf{1} \right) = 1,$$

so that the local particle density (4.6) is fixed. A straightforward calculation yields

$$\mathcal{T} = \frac{\pi^3}{90L} (3\tau^4 + 10\tau^2 + 15), \quad (4.7)$$

and this diverges as $\tau \rightarrow \infty$. The causal structure is more interesting because for large τ , the timelike region shrinks to a small cylinder $r \leq r_{\max}$. More precisely, a Taylor expansion near the origin yields for the two distinct eigenvalues λ_{\pm} of $A(\xi)$

$$(\lambda_+ - \lambda_-)^2 = 16 \left(\frac{1}{4} \frac{\sin Lt}{Lt} \right)^4 (1 + \tau^2) \left(1 - \frac{r^2(6 + \tau^2)}{9} \right) + \mathcal{O}(r^{-4}).$$

Hence the timelike region is given by

$$r < r_{\max} := \frac{3}{\tau} + \mathcal{O}\left(\frac{1}{\tau^3}\right).$$

After verifying that in this region, the two eigenvalues λ_+ and λ_- have the same sign, the action is computed to be

$$\mathcal{S} = \frac{3\pi^2}{5} \frac{1}{L\tau} + \mathcal{O}\left(\frac{1}{\tau^3}\right). \quad (4.8)$$

Hence the action tends to zero as $\tau \rightarrow \infty$. We conclude that $\nu_k := \nu|_{\tau=k}$ is a minimizing sequence of the action \mathcal{S} which does not converge.

It is also worth noting that, according to (4.8) and (4.7), both functionals \mathcal{S} and \mathcal{T} become small if L tends to infinity. Hence dropping the condition $\text{supp } \nu_k \subset \hat{K}$, the sequence $\nu_k := \nu|_{L=k}$ is a minimizing sequence which converges in the $C^0(\hat{M})^*$ -topology to the trivial measure $\nu = 0$. \diamond

A possible method for proving Theorem 4.2 would be to proceed as in Section 3.2 by choosing generators of $P(H)$ and considering the corresponding local correlation matrices. However, since the rank of P may be infinite, it now seems easier to analyze the kernel of the fermionic operator $P(\xi)$ as an operator on the finite-dimensional indefinite inner product space $(V, \langle \cdot | \cdot \rangle)$. This makes it possible to apply similar methods as in the previous chapters, which will be complemented by suitable estimates for negative definite measures. In V we again fix the pseudo-orthonormal basis (e_i) in which the inner product $\langle \cdot | \cdot \rangle$ has the representation (3.13). Furthermore, we denote the sup-norm of matrices in this basis by $\|\cdot\|$ and consider it as a norm on $L(V)$. We say that a linear operator B on V is *positive* if

$$\langle u | Bu \rangle \geq 0 \quad \text{for all } u \in V.$$

Clearly, every positive operator is symmetric in V . However, in contrast to the situation in scalar product spaces, not every positive operator is diagonalizable, as one sees in the simple two-dimensional example

$$B = \begin{pmatrix} 1 & 1 \\ -1 & -1 \end{pmatrix}, \quad S = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

But a positive operator can be diagonalized up to an arbitrarily small error term, as the next lemma shows.

Lemma 4.4. *Suppose that B is a positive linear operator on V . Then for every $\varepsilon > 0$ there is a unitary transformation U on $(V, \langle \cdot | \cdot \rangle)$ such that*

$$UBU^{-1} = -\text{diag}(\nu_1, \dots, \nu_{2n}) + \Delta B,$$

where the real parameters ν_i are ordered as in (2.6) and

$$\|\Delta B\| < \varepsilon.$$

Proof. Suppose that the characteristic polynomial of B has a root $\nu \neq 0$. Then there is a corresponding eigenvector $u \neq 0$. Since $(V, \langle \cdot | \cdot \rangle)$ is non-degenerate, there is a vector $v \in V$ with $\langle v | u \rangle \neq 0$. Then

$$\langle v | Bu \rangle = \nu \langle v | u \rangle \neq 0.$$

Since B is positive, the bilinear form $\langle \cdot | B \cdot \rangle$ is positive semi-definite. The corresponding Schwarz inequality (see [6, Lemma 4.1 (ii)] for details)

$$\langle v | Bu \rangle^2 \leq \langle u | Bu \rangle \langle v | Bv \rangle \tag{4.9}$$

implies that

$$0 < \langle u | Bu \rangle = \nu \langle u | u \rangle.$$

Hence u cannot be a neutral vector. Furthermore, the terms ν and $\langle u | u \rangle$ have the same sign. Introducing the pseudo-normalized vector $f = u / \sqrt{|\langle u | u \rangle|}$, the orthogonal complement of f is an invariant subspace which does not contain u . Hence proceeding inductively, we can diagonalize B except on the invariant subspace corresponding to $\nu = 0$.

Restricting attention to this remaining invariant subspace, the characteristic polynomial of B is trivial. Then B is nilpotent, and thus we can choose a basis where B is a direct sum of Jordan chains. Labeling the Jordan chains by an index c and the basis within each chain by $f_1^{(c)}, \dots, f_{L(c)}^{(c)}$, we have

$$Bf_1^{(c)} = 0 \quad \text{and} \quad Bf_{l+1}^{(c)} = f_l^{(c)}, \quad l \in \{1, \dots, L(c) - 1\}.$$

Let us verify that the inner products between the basis vectors have the properties that

$$\langle f_l^{(c)} | f_{l'}^{(c')} \rangle = 0 \quad \text{unless } L(c) = L(c') \text{ and } l' + l = L(c) + 1. \quad (4.10)$$

To this end, we let c label the longest Jordan chain. Choosing an index $l' < L(c')$, the symmetry of the operator B yields that

$$\langle f_1^{(c)} | f_{l'}^{(c')} \rangle = \langle f_1^{(c)} | Bf_{l'+1}^{(c')} \rangle = \langle Bf_1^{(c)} | f_{l'+1}^{(c')} \rangle = 0.$$

Hence the inner product $\langle f_1^{(c)} | f_{l'}^{(c')} \rangle$ vanishes unless $l' = L(c')$. Next, from the calculation

$$\langle f_1^{(c)} | f_{L(c')}^{(c')} \rangle = \langle B^{L(c)} f_{L(c)}^{(c)} | f_{L(c')}^{(c')} \rangle = \langle f_{L(c)}^{(c)} | B^{L(c)} f_{L(c')}^{(c')} \rangle = 0 \quad \text{if } L(c') < L(c)$$

and the fact that c is the longest Jordan chain, we conclude that

$$\langle f_1^{(c)} | f_{l'}^{(c')} \rangle = 0 \quad \text{unless } l' = L(c') = L(c) =: L.$$

Since $\langle \cdot | \cdot \rangle$ is non-degenerate, we know that there is a Jordan chain c' such that the inner product $\langle f_1^{(c)} | f_{L(c')}^{(c')} \rangle$ is non-zero. If possible, we choose $c' = c$. Then all the inner products between the basis vectors of the chains c and c' can be computed as follows,

$$\langle f_l^{(c)} | f_{l'}^{(c')} \rangle = \langle f_l^{(c)} | B^{L-l'} f_L^{(c')} \rangle = \langle B^{L-l'} f_l^{(c)} | f_L^{(c')} \rangle = \langle f_{l+l'-L}^{(c)} | f_L^{(c')} \rangle,$$

and this vanishes unless $l + l' - L = 1$. Hence (4.10) is satisfied for the chains c and c' . Furthermore, one easily verifies that the subspace of V spanned by the vectors $f_l^{(c)}$ and $f_{l'}^{(c')}$ is non-degenerate. Hence by going over to its orthogonal complement, we can proceed iteratively, proving (4.10).

According to (4.10), all the inner products between the basis vectors remain unchanged if we rescale the basis vectors for any parameter $\rho > 0$ according to

$$f_l^c \rightarrow \rho^{\frac{L(c)+1}{2}-l} f_l^c.$$

But this transformation multiplies all matrix entries of B by a factor ρ^{-1} . Thus by choosing ρ sufficiently large, we can arrange that the matrix entries of B become arbitrarily small. We point out that the Jordan basis is not pseudo-orthonormal. But since the transformation matrix from the Jordan basis to the pseudo-orthonormal basis can be chosen independent of ρ , we can make the matrix entries of B arbitrarily small even in a pseudo-orthonormal basis.

We have shown that there is a pseudo-orthonormal basis (f_i) in which B is diagonal up to an arbitrarily small correction ΔB . Denoting the unitary transformation from the basis (f_i) to our original pseudo-orthonormal basis (e_i) by U (i.e. $U(f_i) = e_i$), the result follows. \square

We next bound the Lagrangian at $\xi = 0$ from below, using a method similar as in [6, Proposition 4.3].

Lemma 4.5. *For every negative definite measure μ , the corresponding Lagrangian (4.5) satisfies at $\xi = 0$ the inequality*

$$\mathcal{L}[\nu](0) \geq \frac{1}{8n^5} |P(0)|^2 \operatorname{Tr}(P(0))^2,$$

where $|\cdot|$ again denotes the spectral weight.

Proof. According to Definition 4.1 (ii), the operator $(-P(0)) = -\nu(\hat{K})$ is positive. Thus applying Lemma 4.4 and taking the limit $\varepsilon \searrow 0$, we conclude that the spectrum of P is real, and that we can order its eigenvalues ν_i counted with algebraic multiplicities as in (2.6). The eigenvalues of $A(0) = P(0)^2$ are then obviously given by $\lambda_i = \nu_i^2 \geq 0$. Hence rewriting the Lagrangian (3.8) according to (2.10) and choosing indices $a, b \in \{1, \dots, 2n\}$ such that $|\nu_a|$ and $|\nu_a| - |\nu_b|$ are maximal, we obtain the estimates

$$\begin{aligned} \mathcal{L}[A(0)] &= \frac{1}{4n} \sum_{i,j=1}^{2n} (\lambda_i - \lambda_j)^2 = \frac{1}{4n} \sum_{i,j=1}^{2n} (|\nu_i| + |\nu_j|)^2 (|\nu_i| - |\nu_j|)^2 \\ &\geq \frac{1}{2n} |\nu_a|^2 (|\nu_a| - |\nu_b|)^2 \geq \frac{1}{8n^3} |P(0)|^2 (|\nu_a| - |\nu_b|)^2 \\ \operatorname{Tr}(P(0)) &= \sum_{k=n+1}^{2n} |\nu_k| - \sum_{l=1}^n |\nu_l| = \frac{1}{n} \sum_{k=n+1}^{2n} \sum_{l=1}^n (|\nu_k| - |\nu_l|) \leq n (|\nu_a| - |\nu_b|). \end{aligned}$$

Combining these inequalities gives the result. \square

Proof of Theorem 4.2. For ease in notation, we omit the brackets $[\nu]$ and replace the arguments $[\nu_k]$ by an index, i.e. $P_k \equiv P[\nu_k]$, $A_k \equiv A[\nu_k]$, $\mathcal{S} \equiv \mathcal{S}[\nu]$, and so on. For any $\varepsilon > 0$ and $k \in \mathbb{N}$, we apply Lemma 4.4 to the operator $B = -\nu_k(\hat{K})$, which is positive according to (4.2). Replacing the measures ν_k by $U\nu_k U^{-1}$, we conclude that

$$\nu_k(\hat{K}) = \operatorname{diag}(\nu_1^{(k)}, \dots, \nu_{2n}^{(k)}) + \Delta\nu_k \quad \text{with} \quad \|\Delta\nu_k\| \leq \varepsilon \quad (4.11)$$

(where we again work in the pseudo-orthonormal basis (e_i)). Our main task is to show that the measures ν_k are uniformly bounded in the sense that there is a constant $C > 0$ such that

$$\|\nu_k(\Omega)\| \leq C \quad \text{for all } k \in \mathbb{N} \text{ and all Borel sets } \Omega \subset \hat{K}. \quad (4.12)$$

We first complete the proof of the theorem assuming this uniform bound, which we shall prove afterwards. If (4.12) holds, the Banach-Alaoglu theorem and the Riesz representation theorem yield that a subsequence of the ν_k converges in the $C^0(\hat{K})^*$ -topology to a negative definite measure ν . Thus the integral (4.3) converges pointwise,

$$P_k(\xi) \rightarrow P(\xi) \quad \text{for every } \xi \in M.$$

As a consequence, the spectral weight $|A_k(\xi)|$ converges pointwise. Using that the spectral weight is non-negative, we can apply Fatou's lemma to obtain

$$\mathcal{T} = \int_M \lim_{k \rightarrow \infty} |A_k(\xi)|^2 d^4\xi \leq \lim_{k \rightarrow \infty} \int_M |A_k(\xi)|^2 d^4\xi = \lim_{k \rightarrow \infty} \mathcal{T}_k.$$

Similarly, one sees that $\mathcal{S} \leq \lim_{k \rightarrow \infty} \mathcal{S}_k$. This concludes the proof provided that (4.12) holds.

To prove (4.12), we first make use of the positivity property (ii) in Definition 4.1. Namely, this property ensures that for any Borel set $\Omega \subset \hat{K}$, the bilinear form $\langle \cdot | (-\nu_k(\Omega)) \cdot \rangle$ is positive semi-definite. Thus the Schwarz inequality yields

$$(\langle e_i | (-\nu_k(\Omega)) e_j \rangle)^2 \leq \langle e_i | (-\nu_k(\Omega)) e_i \rangle \langle e_j | (-\nu_k(\Omega)) e_j \rangle .$$

In other words, the off-diagonal diagonal matrix elements are bounded in terms of the diagonal entries, and thus it suffices to show that the diagonal entries $\langle e_i | (-\nu_k(\Omega)) e_i \rangle$ are bounded. Furthermore, in view of the fact that the measures $\langle e_i | (-\nu_k(\cdot)) e_i \rangle$ are all positive, it suffices to show that the total measure is bounded, i.e.

$$|\langle e_i | \nu_k(\hat{K}) e_i \rangle| \leq C \quad \text{for all } k \in \mathbb{N}.$$

Applying (4.11) and taking the limit $\varepsilon \searrow 0$, this condition reduces to demanding that the spectral weight of $\nu_k(\hat{K})$ be bounded,

$$|\nu_k(\hat{K})| \leq C \quad \text{for all } k \in \mathbb{N}. \quad (4.13)$$

In case (II) when μ is a counting measure, it is obvious that $\mathcal{L}_k(0) \leq \mathcal{S}_k$. Thus Lemma 4.5 yields

$$|P_k(0)|^2 \leq 8n^5 \frac{\mathcal{S}_k}{|\text{Tr}(P_k(0))|^2} .$$

In view of (4.6) and the uniform boundedness of the action, we thus have a uniform a-priori bound for the spectral weight of $P_k(0)$. Using that $P_k(0) = \nu_k(\hat{K})$, we obtain (4.13).

In case (I) and if μ is the counting measure, the uniform boundedness of the functional \mathcal{T} yields that the spectral weight $|A_k(0)|$ is uniformly bounded. Since $A_k(0) = P_k(0)^2$, it follows that the spectral weight of $P_k(0)$ is also uniformly bounded, proving (4.13). Thus it remains to consider case (I) for μ the Lebesgue measure. This is the most difficult case, because we need to bound the space-time integral (4.5) from below by $|P(0)|$, making it necessary to estimate $|A(\xi)|$ in a neighborhood of $\xi = 0$. We introduce the quantity $\Delta P(\xi) = P(\xi) - P(0)$. Using (4.3), we obtain

$$\|\Delta P_k(\xi)\| \leq \int_{\hat{K}} \left| e^{i\langle p, \xi \rangle} - 1 \right| d\|\nu_k(p)\| \leq \text{diam}(\hat{K}) \|\xi\| \|\nu_k\|(\hat{K}), \quad (4.14)$$

where $\|\xi\|$ is the Euclidean norm on \mathbb{R}^4 , and the norm of the measure is defined by

$$\|\nu\|(\hat{K}) = \sum_{i,j=1}^{2n} |\langle e_i | \nu e_j \rangle|(\hat{K})$$

(and $|\langle e_i | \nu e_j \rangle|$ denotes the variation of a complex-valued measure, see [10, Sections 28 and 29]). In order to estimate this norm, we first note that the Schwarz inequality (4.9) allows us to estimate the off-diagonal elements $|\langle e_i | \nu e_j \rangle|(\hat{K})$ in terms of the diagonal elements. For the diagonal elements, on the other hand, we can use that $-\langle e_i | \nu e_i \rangle$ is a positive measure. Hence

$$\|\nu(\hat{F})\| \leq n |\nu(\hat{F})| .$$

Using this inequality in (4.14), we conclude that

$$\|\Delta P_k(\xi)\| \leq \int_{\hat{K}} \left| e^{i\langle p, \xi \rangle} - 1 \right| d\|\nu_k(p)\| \leq n \text{diam}(\hat{K}) \|\xi\| |\nu_k(\hat{K})| .$$

We choose ξ so small that

$$\|\xi\| \leq \frac{1}{8n \operatorname{diam}(\hat{K})}. \quad (4.15)$$

Then $P_k(\xi)$ has the representation

$$P_k(\xi) = P_k(0) + \Delta P_k(\xi) \quad \text{with} \quad \|\Delta P_k(\xi)\| \leq \frac{1}{8} |P_k(0)|.$$

Multiplying by a similar representation for $P_k(-\xi)$ and using that, according to (4.11), the matrix $P_k(0)$ is diagonal up to an arbitrarily small error term, we conclude that

$$A_k(\xi) = A_k(0) + \Delta A_k(\xi) \quad \text{with} \quad \|\Delta A_k(\xi)\| \leq \frac{1}{2} |A_k(0)|.$$

Now ΔA can be treated as a perturbation. Using that the deviation of the eigenvalues is bounded by the sup-norm of the perturbation (see [13, Chapter Two, §1]), we obtain the following estimate for the local trace,

$$|A_k(\xi)| \geq \frac{1}{2} |A_k(0)|.$$

Hence integrating over the ball (4.15), we obtain the inequality

$$\mathcal{T}_k \geq \frac{|A_k(0)|^2}{4} \frac{\pi^2}{2} \left(8n \operatorname{diam}(\hat{K})\right)^{-4},$$

giving us the desired a-priori bound for the spectral weight $|A_k(0)|$. Again using that $A_k(0) = P_k(0)^2$, it follows that the spectral weight of $P_k(0)$ is uniformly bounded, proving (4.13). \square

Acknowledgments: I would like to thank Andreas Grotz, Joel Smoller, Daniela Schiefeneder and the referee for helpful comments on the manuscript.

REFERENCES

- [1] J. Bognár, *Indefinite inner product spaces*, Springer-Verlag, New York, 1974, *Ergebnisse der Mathematik und ihrer Grenzgebiete, Band 78*.
- [2] A. Diethert, F. Finster, and D. Schiefeneder, *Fermion systems in discrete space-time exemplifying the spontaneous generation of a causal structure*, arXiv:0710.4420 [math-ph], *Int. J. Mod. Phys. A* **23** (2008), no. 27/28, 4579–4620.
- [3] F. Finster, *The principle of the fermionic projector*, hep-th/0001048, hep-th/0202059, hep-th/0210121, *AMS/IP Studies in Advanced Mathematics*, vol. 35, American Mathematical Society, Providence, RI, 2006.
- [4] ———, *The principle of the fermionic projector: an approach for quantum gravity?*, arXiv:gr-qc/0601128, *Quantum gravity* (B. Fauser, J. Tolksdorf, and E. Zeidler, eds.), Birkhäuser, Basel, 2006, pp. 263–281.
- [5] ———, *Fermion systems in discrete space-time—outer symmetries and spontaneous symmetry breaking*, arXiv:math-ph/0601039, *Adv. Theor. Math. Phys.* **11** (2007), no. 1, 91–146.
- [6] ———, *A variational principle in discrete space-time: existence of minimizers*, arXiv:math-ph/0503069, *Calc. Var. Partial Differential Equations* **29** (2007), no. 4, 431–453.
- [7] ———, *From discrete space-time to Minkowski space: basic mechanisms, methods and perspectives*, arXiv:0712.0685 [math-ph], *Quantum Field Theory* (B. Fauser, J. Tolksdorf, and E. Zeidler, eds.), Birkhäuser Verlag, 2009, pp. 235–259.
- [8] J. Glimm and A. Jaffe, *Quantum physics, a functional integral point of view*, second ed., Springer-Verlag, New York, 1987.
- [9] I. Gohberg, P. Lancaster, and L. Rodman, *Indefinite linear algebra and applications*, Birkhäuser Verlag, Basel, 2005.

- [10] P.R. Halmos, *Measure theory*, Springer, New York, 1974.
- [11] S. Helgason, *Groups and geometric analysis*, Mathematical Surveys and Monographs, vol. 83, American Mathematical Society, Providence, RI, 2000, Integral geometry, invariant differential operators, and spherical functions, Corrected reprint of the 1984 original.
- [12] R.A. Johnson, *Atomic and nonatomic measures*, Proc. Amer. Math. Soc. **25** (1970), 650–655.
- [13] T. Kato, *Perturbation theory for linear operators*, Classics in Mathematics, Springer-Verlag, Berlin, 1995, Reprint of the 1980 edition.
- [14] M. Reed and B. Simon, *Methods of modern mathematical physics. I, functional analysis*, second ed., Academic Press Inc., New York, 1980.
- [15] W. Rudin, *Functional analysis*, second ed., International Series in Pure and Applied Mathematics, McGraw-Hill Inc., New York, 1991.
- [16] E.B. Saff and A.B.J. Kuijlaars, *Distributing many points on a sphere*, Math. Intelligencer **19** (1997), no. 1, 5–11.
- [17] D. Serre, *Matrices*, Graduate Texts in Mathematics, vol. 216, Springer-Verlag, New York, 2002, Theory and applications, Translated from the 2001 French original.

NWF I - MATHEMATIK, UNIVERSITÄT REGENSBURG, D-93040 REGENSBURG, GERMANY
E-mail address: `Felix.Finster@mathematik.uni-regensburg.de`